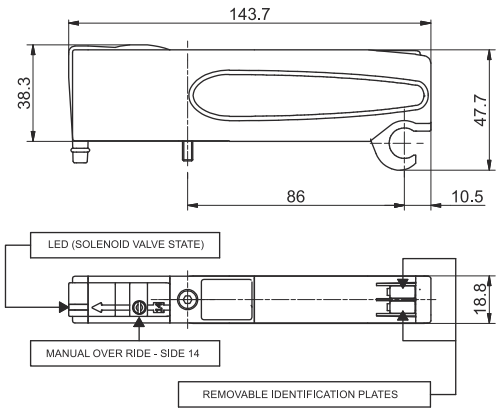
2

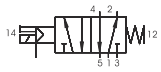
Solenoid - Spring

Ordering code

2541.52.00.39.Ⓥ

Ⓥ	VOLTAGE
	02 = 24 VDC PNP
	12 = 24 VDC NPN
	05 = 24 VAC





SHORT FUNCTION CODE "A"
"Shifting time of pneumatic directional control valves or moving parts, logic devices were measured in accordance to ISO 12238:2001, Pneumatic fluid power - Directional control valves - Measurement of shifting time."

Operational characteristic

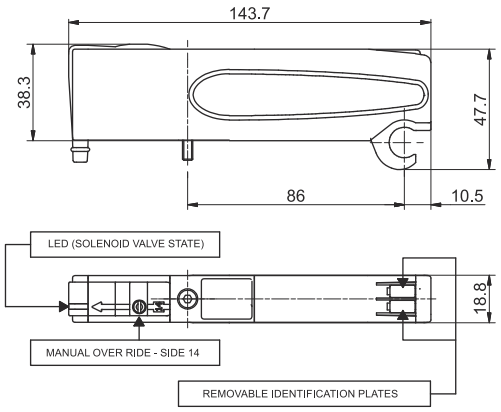
Fluid	Flow rate at 6 bar with Δp=1 (Nl/min)	Responce time according to ISO 12238, activation time (ms)	Responce time according to ISO 12238, deactivation time (ms)	Working pressure (bar)	Pressure range (bar) pilots 12-14	Temperature °C	Weight (gr.)
Filtered air, with or without lubrication	750	14	40	From vacuum to 10	3 - 7 bar	-5° / +50°	129

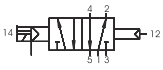
Solenoid - Differential

Ordering code

2541.52.00.36.Ⓥ

Ⓥ	VOLTAGE
	02 = 24 VDC PNP
	12 = 24 VDC NPN
	05 = 24 VAC





SHORT FUNCTION CODE "B"
"Shifting time of pneumatic directional control valves or moving parts, logic devices were measured in accordance to ISO 12238:2001, Pneumatic fluid power - Directional control valves - Measurement of shifting time."

Operational characteristic

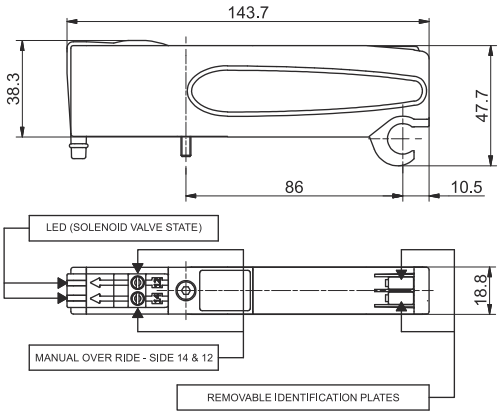
Fluid	Flow rate at 6 bar with Δp=1 (Nl/min)	Responce time according to ISO 12238, activation time (ms)	Responce time according to ISO 12238, deactivation time (ms)	Working pressure (bar)	Pressure range (bar) pilots 12-14	Temperature °C	Weight (gr.)
Filtered air, with or without lubrication	750	20	29	From vacuum to 10	3 - 7 bar	-5° / +50°	126

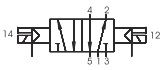
Solenoid - Solenoid

Ordering code

2541.52.00.35.Ⓥ

Ⓥ	VOLTAGE
	02 = 24 VDC PNP
	12 = 24 VDC NPN
	05 = 24 VAC





SHORT FUNCTION CODE "C"
"Shifting time of pneumatic directional control valves or moving parts, logic devices were measured in accordance to ISO 12238:2001, Pneumatic fluid power - Directional control valves - Measurement of shifting time."

Operational characteristic

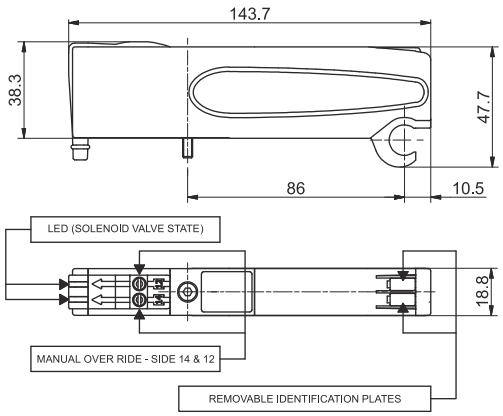
Fluid	Flow rate at 6 bar with Δp=1 (Nl/min)	Responce time according to ISO 12238, activation time (ms)	Responce time according to ISO 12238, deactivation time (ms)	Working pressure (bar)	Pressure range (bar) pilots 12-14	Temperature °C	Weight (gr.)
Filtered air, with or without lubrication	750	10	14	From vacuum to 10	3 - 7 bar	-5° / +50°	134

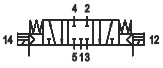
Solenoid - Solenoid - (5/3 Closed centres)

Ordering code

2541.53.31.35.Ⓥ

	VOLTAGE
Ⓥ	02 = 24 VDC PNP
	12 = 24 VDC NPN
	05 = 24 VAC





SHORT FUNCTION CODE "E"
"Shifting time of pneumatic directional control valves or moving parts, logic devices were measured in accordance to ISO 12238:2001, Pneumatic fluid power - Directional control valves - Measurement of shifting time."

Operational characteristic

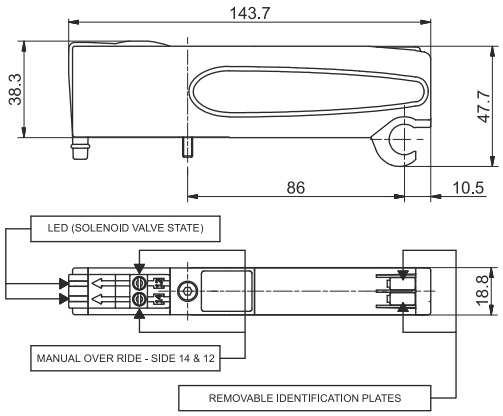
Fluid	Flow rate at 6 bar with Δp=1 (Nl/min)	Responce time according to ISO 12238, activation time (ms)	Responce time according to ISO 12238, deactivation time (ms)	Working pressure (bar)	Pressure range (bar) pilots 12-14	Temperature °C	Weight (gr.)
Filtered air, with or without lubrication	600	15	20	From vacuum to 10	3 - 7 bar	-5° / +50°	132

Solenoid - Solenoid 2x3/2

Ordering code

2541.62.Ⓕ.35.Ⓥ

	FUNCTION
	44 = NC - NC (5/3 Open centres)
Ⓕ	55 = NO - NO (5/3 Pressured centres)
	45 = NC - NO (Normally Closed - Normally Open)
	54 = NO - NC (Normally Open - Normally Closed)
	VOLTAGE
Ⓥ	02 = 24 VDC PNP
	12 = 24 VDC NPN
	05 = 24 VAC



SHORT FUNCTION CODE:
NC-NC (5/3 Open centres) = "F"
NO-NC (5/3 Pressured centres) = "G"
NC-NO = "H"

"Shifting time of pneumatic directional control valves or moving parts, logic devices were measured in accordance to ISO 12238:2001, Pneumatic fluid power - Directional control valves - Measurement of shifting time."

Operational characteristic

"Example: If inlet pressure is set at 5bar then pilot pressure must be at least Pp=2,5+(0.2*5)=3,5bar"

Fluid	Flow rate at 6 bar with Δp=1 (Nl/min)	Responce time according to ISO 12238, activation time (ms)	Responce time according to ISO 12238, deactivation time (ms)	Working pressure (bar)	Pressure range (bar) pilots 12-14	Temperature °C	Weight (gr.)
Filtered air, with or without lubrication	700	15	25	From vacuum to 10	≥2,5+(0,2xP.alim.)	-5° / +50°	122

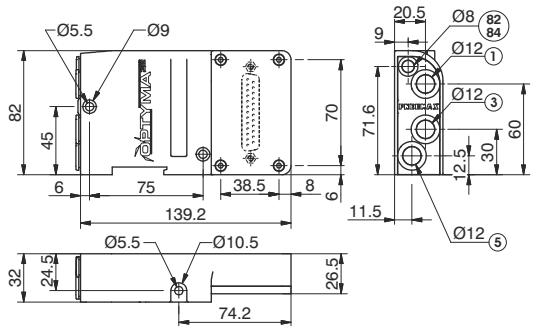
2

Right Endplates

Ordering code

2540.03.Ⓒ

Ⓒ	CONNECTOR TYPE
	00 = Exhaust electrical connection closed
	25P = Connectors 25 poles



Weight gr. 274

CONDUIT 82/84= DO NOT PRESSURIZE, SOLENOID PILOTS EXHAUST

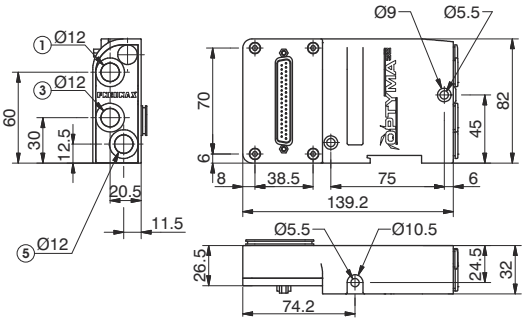
Operating Characteristics	Fluid	Pressure range (bar)	Temperature °C
	Filtered and lubricated air or not	From vacuum to 10	-5 - +50

Left Endplates - External feeding base

Ordering code

2540.02.Ⓒ

Ⓒ	CONNECTOR TYPE
	37P = Connector 37 poles PNP
	25P = Connector 25 poles PNP
	37N = Connector 37 poles NPN
	25N = Connector 25 poles NPN
	37A = Connector 37 poles AC
	25A = Connector 25 poles AC



Weight gr. 300

12/14 divided from conduct 1

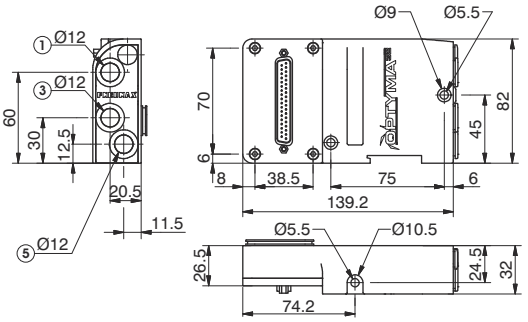
Operating Characteristics	Fluid	Pressure range (bar)	Pilot working pressure (bar)	Temperature °C
	Filtered and lubricated air or not	From vacuum to 10	3 - 7	-5 - +50

Left Endplates - Self-feeding Base

Ordering code

2540.12.Ⓒ

Ⓒ	CONNECTOR TYPE
	37P = Connector 37 poles PNP
	25P = Connector 25 poles PNP
	37N = Connector 37 poles NPN
	25N = Connector 25 poles NPN
	37A = Connector 37 poles AC
	25A = Connector 25 poles AC



Weight gr. 300

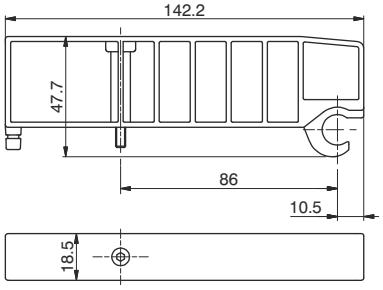
12/14 connected with conduct 1

Operating Characteristics	Fluid	Pilot working pressure (bar)	Temperature °C
	Filtered and lubricated air or not	3 - 7	-5 - +50

Closing plate

Ordering code

2530.00



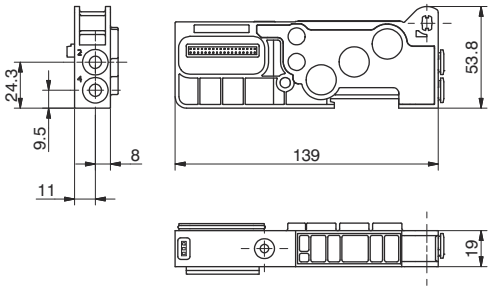
Weight gr. 53,5
SHORT FUNCTION CODE "T"

Operating Characteristics	Fluid	Pressure range (bar)	Temperature °C
	Filtered and lubricated air or not	From vacuum to 10	-5 - +50

Modular base

Ordering code
254Ⓒ.01Ⓥ

	CONNECTIONS
Ⓣ	1 = G1/8" Female
	4 = Cartridge Ø 4
	6 = Quick fitting tube Ø 6
	8 = Quick fitting tube Ø 8
	VERSION
Ⓥ	M= Monostable
	B= Bistable

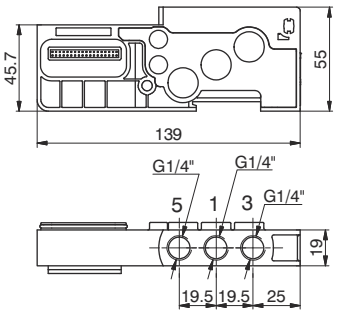


Weight gr. 96,5

Operating Characteristics	Fluid	Pressure range (bar)	Temperature °C
	Filtered and lubricated air or not	From vacuum to 10	-5 - +50

Intermediate Inlet/Exhaust module

Ordering code
2540.10

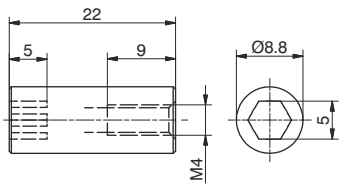


Weight gr. 115
SHORT FUNCTION CODE "W"

Operating Characteristics	Fluid	Pressure range (bar)	Temperature °C
	Filtered and lubricated air or not	From vacuum to 10	-5 - +50

Nut

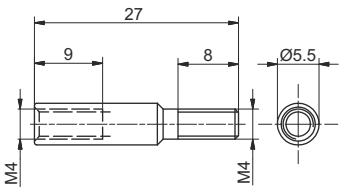
Ordering code
2540.KD.00



Weight gr. 10
The Kit includes 4 pieces

Extension (1 Position)

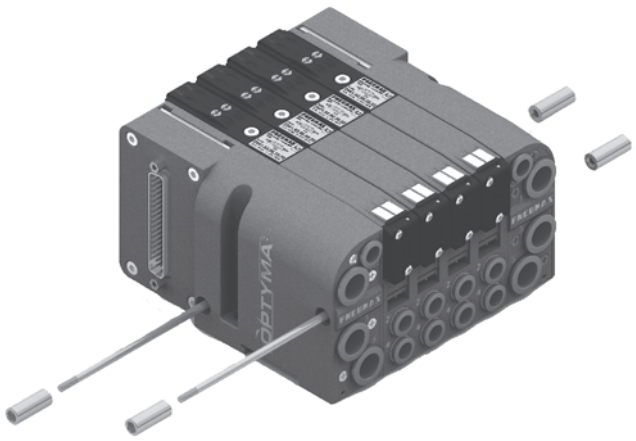
Ordering code
2540.KP.01

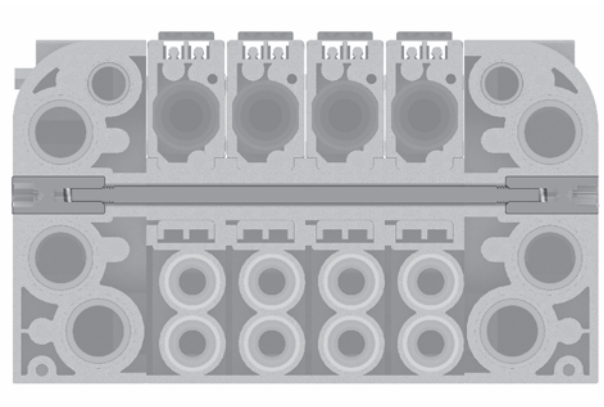


Weight gr. 3,5
The Kit includes 2 pieces

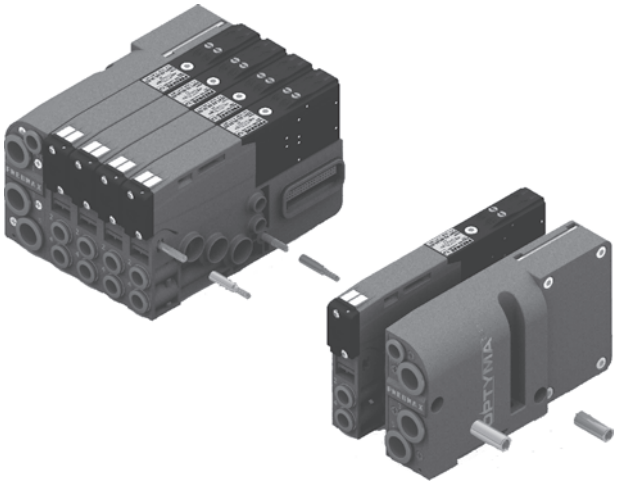
2

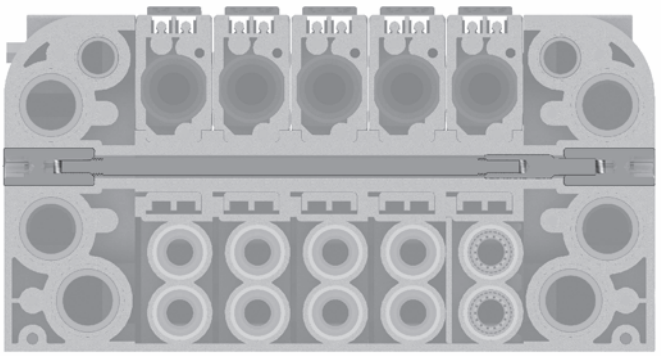
Set with single tie-rod (max. 32 Solenoid valves)





Set with tie-rod, more extension adding a valve



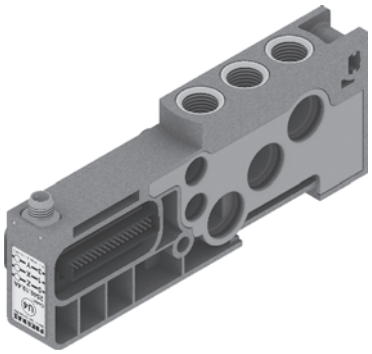


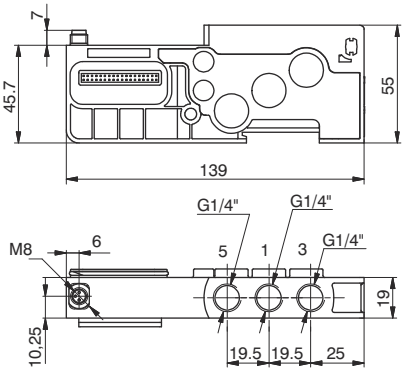
General :

Each Optyma-T manifold lets to manage 32 command signals for the valves.
Optyma-T serial nodes (CANopen®, DeviceNet, PROFIBUS DP, EtherCAT®, PROFINET IO RT/IRT, EtherNet/IP and Powerlink) have a single pin for the power supply of the solenoid valves. So if you want to interrupt the power supply of one valve it is necessary to interrupt all the valves. The additional power supply module lets to interrupt at the same time the first 2 available command signals for the valves after the module itself. The additional power supply module is particularly useful also when you use control signals that block the valves. This application is effective both with serial management and multi-pole connection of the manifolds.
This module is inserted directly into the Optyma-T solenoid valves manifold.

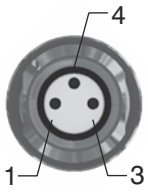
Ordering code

2540.10.2A





In particular this module is fitted with a M8 3 pins connector:
+24V, not connected, GND.



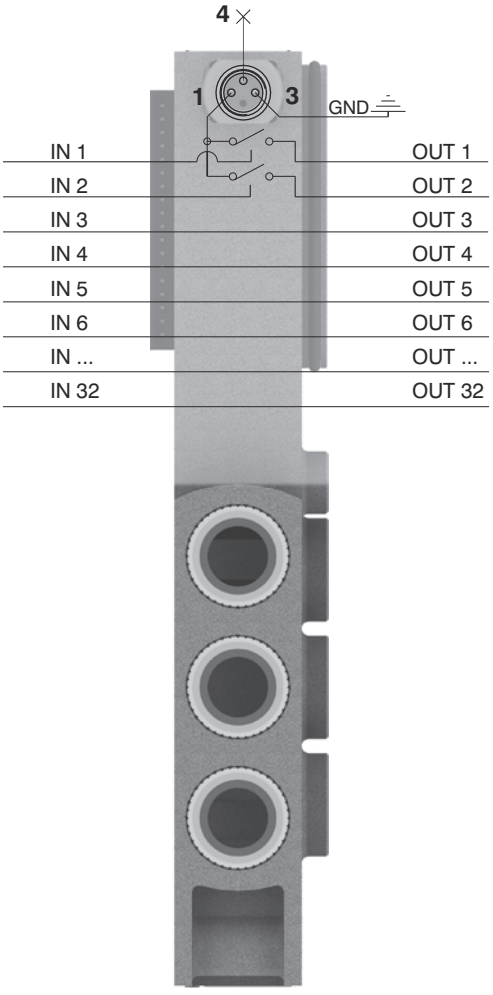
PIN	DESCRIPTION
1	+24 VDC
4	NOT CONNECTED
3	GND

WORKING PRINCIPLE / SIMPLIFIED FUNCTIONAL DIAGRAM

This module uses an external power supply (+24VDC) to manage the solenoid valves.

The output signal from serial node / multi-pole connection is used as command signal: when it is high the +24VDC will be present at the module output.

If you want to cut off the power supply to a group of 2 valves it is sufficient to take away the +24VDC provided to the module by the M8 connector.



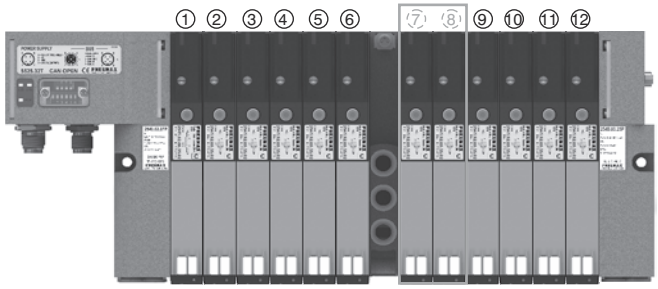
Please note: It is possible to use more modules to interrupt all the command signals, simply by inserting them before the signals to interrupt and after the signals already interrupted.

2

Usage examples:

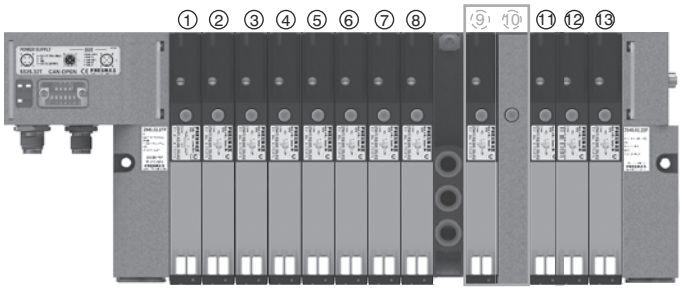
EXAMPLE 1:
Manifold of 12 monostable valves on which you want to interrupt signals 7-8

Assembly:
- 6 monostable valves (not interruptible because before the module),
- 1 additional power supply module,
- 6 monostable valves. Please note: the first 2 monostable of these are interruptible by the module, while the following 4 will work correctly managed directly by the corresponding command signals.



EXAMPLE 2:
Manifold of 12 monostable valves on which you want to interrupt signal 9

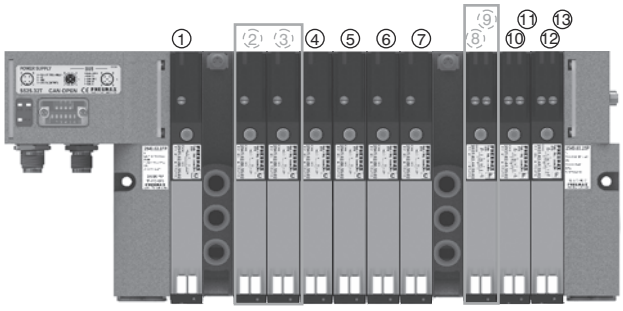
Assembly:
- 8 monostable valves (not interruptible because before the module),
- 1 additional power supply module,
- 1 monostable valve (interruptible),
- 1 closing plate mounted on a monostable base,
- 3 monostable valves (work correctly managed directly by the corresponding command signals).



Please note: Each additional power supply module interrupts always 2 electrical signals.
If you need to interrupt less than 2 signals you can:
- assemble the valves to interrupt in the last positions of the manifold, so you don't need to worry about the interrupted exceeding signals;
- use a bistable base and mount a monostable valve (for each signal less than the 2 standard);
- use a monostable base and mount a closing plate (for each signal less than the 2 standard).

EXAMPLE 3:
Manifold of 7 monostable e 3 bistable valves on which you want to interrupt signals 2-3 and 8-9.

Assembly:
- 1 monostable valve (not interruptible because before the module),
- 1 additional power supply module,
- 6 monostable valves.
Please note: the first 2 monostable of these are interruptible by the module, while the following 4 will work correctly managed directly by the corresponding command signals.
- 1 additional power supply module,
- 3 bistable valves.
Please note: the first bistable of these valves is interruptible by the module, while the following 2 will work correctly managed directly by the corresponding command signals.

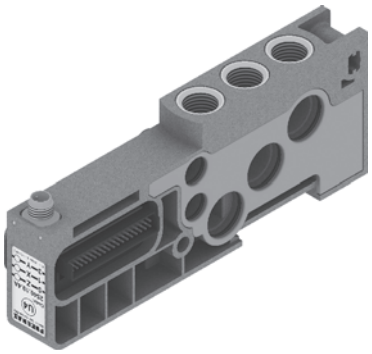


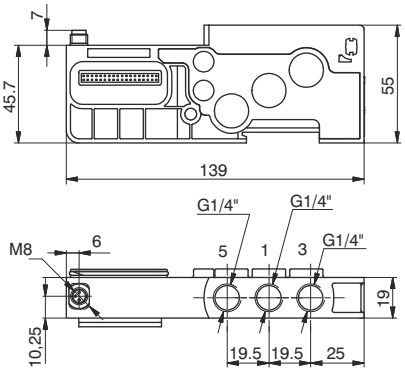
General :

Each Optyma-T manifold lets to manage 32 command signals for the valves.
Optyma-T serial nodes (CANopen®, DeviceNet, PROFIBUS DP, EtherCAT®, PROFINET IO RT/IRT, EtherNet/IP and Powerlink) have a single pin for the power supply of the solenoid valves. So if you want to interrupt the power supply of one valve it is necessary to interrupt all the valves.
The additional power supply module lets to interrupt at the same time the first 4 available command signals for the valves after the module itself. The additional power supply module is particularly useful also when you use control signals that block the valves. This application is effective both with serial management and multi-pole connection of the manifolds.
This module is inserted directly into the Optyma-T solenoid valves manifold.

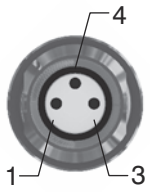
Ordering code

2540.10.4A





In particular this module is fitted with a M8 3 pins connector:
+24V, not connected, GND.



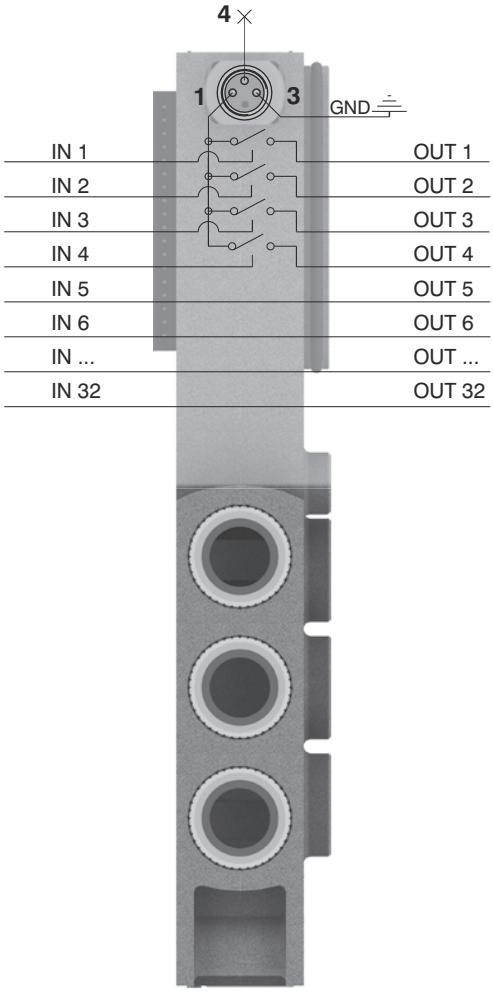
PIN	DESCRIPTION
1	+24 VDC
4	NOT CONNECTED
3	GND

WORKING PRINCIPLE / SIMPLIFIED FUNCTIONAL DIAGRAM

This module uses an external power supply (+24VDC) to manage the solenoid valves.

The output signal from serial node / multi-pole connection is used as command signal: when it is high the +24VDC will be present at the module output.

If you want to cut off the power supply to a group of 4 valves it is sufficient to take away the +24VDC provided to the module by the M8 connector.

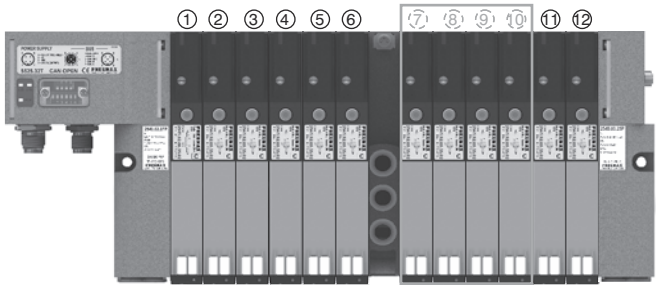


Please note: It is possible to use more modules to interrupt all the command signals, simply by inserting them before the signals to interrupt and after the signals already interrupted.

Usage examples:

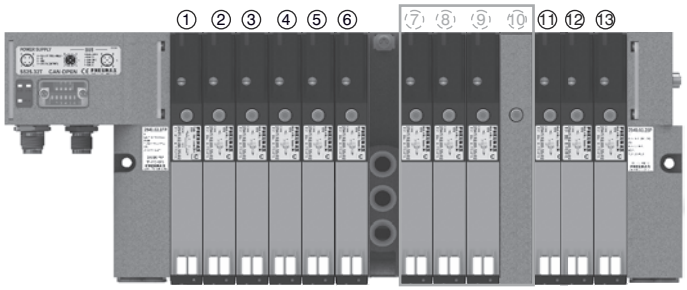
EXAMPLE 1:
Manifold of 12 monostable valves on which you want to interrupt signals 7-8-9-10

Assembly:
- 6 monostable valves (not interruptible because before the module),
- 1 additional power supply module,
- 6 monostable valves. Please note: the first 4 monostable of these are interruptible by the module, while the following 2 will work correctly managed directly by the corresponding command signals.



EXAMPLE 2:
Manifold of 12 monostable valves on which you want to interrupt signals 7-8-9

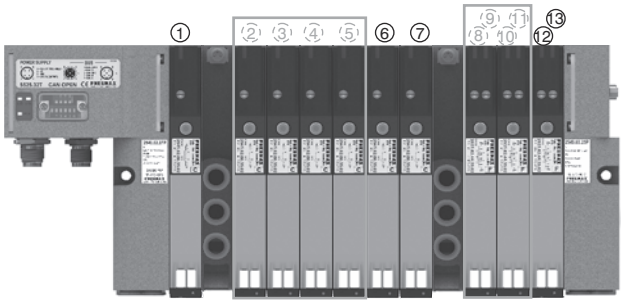
Assembly:
- 6 monostable valves (not interruptible because before the module),
- 1 additional power supply module,
- 3 monostable valves (interruptible),
- 1 closing plate mounted on a monostable base,
- 3 monostable valves (work correctly managed directly by the corresponding command signals).



Please note: Each additional power supply module interrupts always 4 electrical signals.
If you need to interrupt less than 4 signals you can:
- assemble the valves to interrupt in the last positions of the manifold, so you don't need to worry about the interrupted exceeding signals;
- use a bistable base and mount a monostable valve (for each signal less than the 4 standard);
- use a monostable base and mount a closing plate (for each signal less than the 4 standard).

EXAMPLE 3:
Manifold of 7 monostable e 3 bistable valves on which you want to interrupt signals 2-3-4-5 and 8-9-10-11.

Assembly:
- 1 monostable valve (not interruptible because before the module),
- 1 additional power supply module,
- 6 monostable valves.
Please note: the first 4 monostable of these are interruptible by the module, while the following 2 will work correctly managed directly by the corresponding command signals.
- 1 additional power supply module,
- 3 bistable valves.
Please note: the first 2 bistable of these valves are interruptible by the module, while the following will work correctly managed directly by the corresponding command signals.



Tie-rod M4

Ordering code
2540.KT.P

	N. POSITIONS
P	01=Nr. 1 Position
	02=Nr. 2 Positions
	03=Nr. 3 Positions
	04=Nr. 4 Positions
	05=Nr. 5 Positions
	06=Nr. 6 Positions
	07=Nr. 7 Positions
	08=Nr. 8 Positions
	09=Nr. 9 Positions
	10=Nr. 10 Positions
	11=Nr. 11 Positions
	12=Nr. 12 Positions
	13=Nr. 13 Positions
	14=Nr. 14 Positions
	...
	32=Nr. 32 Positions

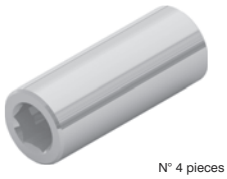
CODE LIST

CODE	"L" DIMENSION
2540.KT.01	55
2540.KT.02	74
2540.KT.03	93
2540.KT.04	112
2540.KT.05	131
2540.KT.06	150
2540.KT.07	169
2540.KT.08	188
2540.KT.09	207
2540.KT.10	226
2540.KT.11	245
2540.KT.12	264
2540.KT.13	283
2540.KT.14	302
2540.KT. ...	...
2540.KT.32	644

Accessories table for manifolds

Set of N° positions	Ordering code
1	2540.KD.00 + 2540.KT.01
2	2540.KD.00 + 2540.KT.02
3	2540.KD.00 + 2540.KT.03
4	2540.KD.00 + 2540.KT.04
5	2540.KD.00 + 2540.KT.05
6	2540.KD.00 + 2540.KT.06
7	2540.KD.00 + 2540.KT.07
8	2540.KD.00 + 2540.KT.08
9	2540.KD.00 + 2540.KT.09
10	2540.KD.00 + 2540.KT.10
11	2540.KD.00 + 2540.KT.11
12	2540.KD.00 + 2540.KT.12
13	2540.KD.00 + 2540.KT.13
14	2540.KD.00 + 2540.KT.14
15	2540.KD.00 + 2540.KT.15
16	2540.KD.00 + 2540.KT....
32	2540.KD.00 + 2540.KT.32

2540.KD.00



N° 4 pieces

2540.KT.XX

N° 2 pieces

Polyethylene Silencer Series SPL-R

Ordering code
SPLR.F

	TUBE DIAMETER
F	8=8 mm
	12=12 mm

Diaphragm plug

Ordering code
2530.17
Weight gr. 6,5

Cable complete with connector, 25 Poles IP65

Ordering code
2300.25.L.C

	CABLE LENGHT
L	03 = 3 meters
	05 = 5 meters
	10 = 10 meters
	CONNECTORS
P	10 = In line
	90 = 90° Angle

Cable complete with connector, 37 Poles IP65

Ordering code
2400.37.L.C

	CABLE LENGHT
L	03 = 3 meters
	05 = 5 meters
	10 = 10 meters
	CONNECTORS
P	10 = In line
	90 = 90° Angle

Cable complete with connector, 25 Poles IP65

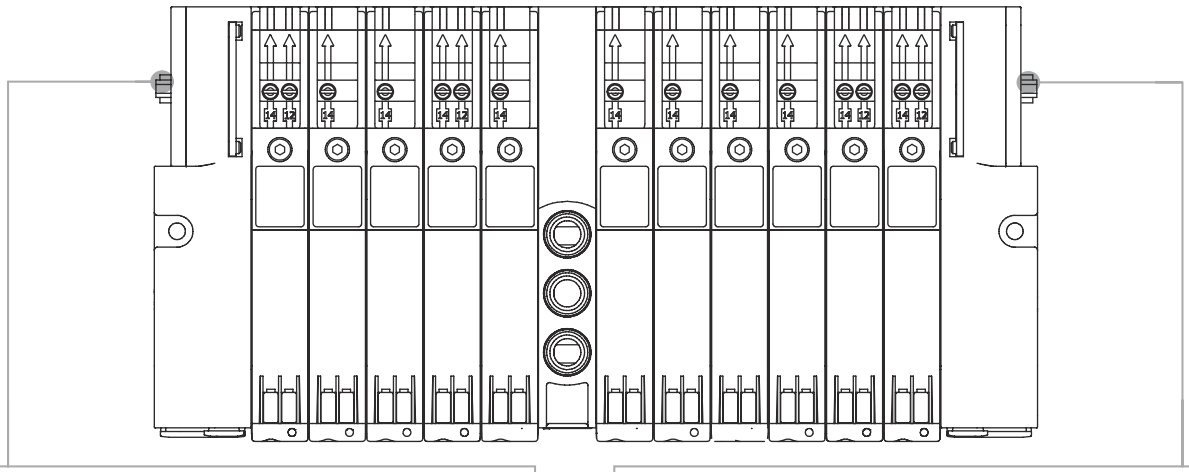
Ordering code
2400.25.L.25

	CABLE LENGHT
L	03 = 3 meters
	05 = 5 meters
	10 = 10 meters

The electrical connection is achieved by a 37 pin connector and can manage up to 32 solenoid pilots.
It is also possible use a 25 sub-D pin connector and, in this case, it is possible to manage a maximum of 22 outputs.
The management and distribution of the electrical signals between each valve is obtained thanks to an electrical connector which receives the signals from the previous module, uses one, two or none depending on the type, and carries forward to the next module the remaining.
Bistable valves, 5/3 and 2x3/2 valves which have two solenoid pilots built in, use two signals; the first is directed to the pilot side 14 the second to the pilot side 12. Modular bases can be fitted with two type of electrical connector: the monostable version uses only one signal (connected to the pilot side 14) and carries forward the remaining, the bistable version which always uses two signals.
This solution allows the modification of the manifold (replacement of monostable valves without bistable for example) without having to reset the PLC output layout.
On other hand this solution limits the maximum number of valves to 16 when it is used a 37 pin connector or 11 when it is used a 25 pin connector.
Intermediate supply/exhaust module uses an electrical connector directly forwarding signals to the next one without any kind of modification.
This allows the use of intermediate modules in any position of the manifold.
All the electrical signals that have not been used on the manifold can be used placing at the end of the manifold the end plate complete with the 25 sub-D female connector.
The number of available signals depends of the connector used to the type of the left end plate and by the total signals used along the manifold:

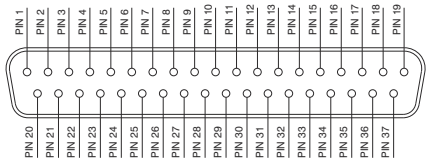
37 pin connector nr of output = 32 – (total of used signals)
25 pin connector nr of output = 22 – (total of used signals)

Following we show some examples of possible combination and the relative pin assignment.



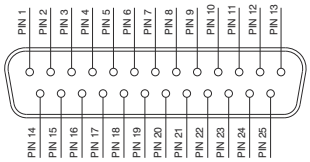
IN-LET ELECTRIC CONNECTIONS

SUB-D 37 POLE
MALE CONNECTOR



1 - 32 = SOLENOID VALVES SIGNAL
33 - 35 = GND
36 - 37 = THROUGH LINE

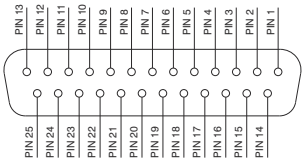
SUB-D 25 POLE
MALE CONNECTOR



1 - 22 = SOLENOID VALVES SIGNAL
23 - 24 = GND
25 = THROUGH LINE

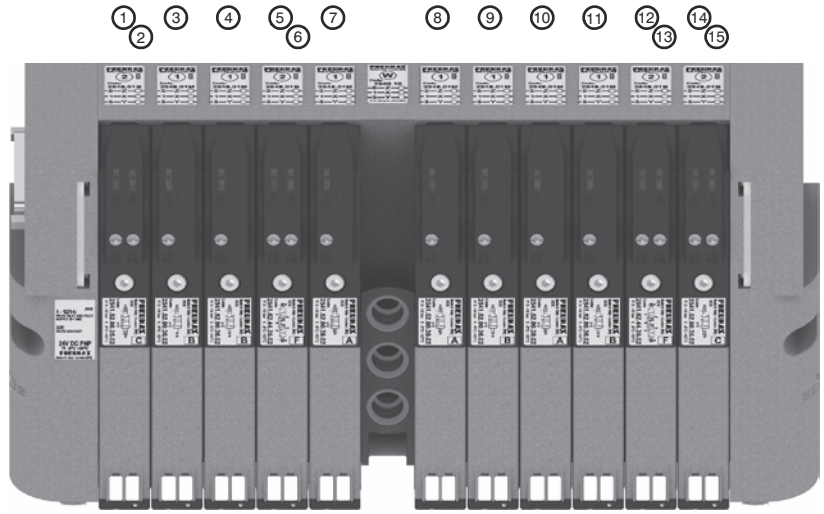
OUTLET ELECTRIC CONNECTIONS (IF PRESENT)

SUB-D 25 POLE
FEMALE CONNECTOR



1 - 22 = SOLENOID VALVES SIGNAL
23 - 24 = GND
25 = THROUGH

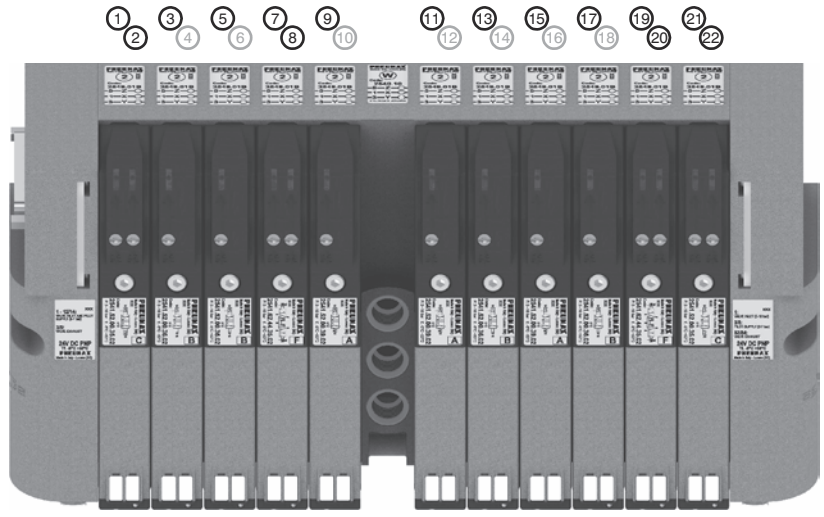
37 PIN Connector correspondence for valves assembled on mixed bases



PIN 1 = PILOT 14 EV POS.1
PIN 2 = PILOT 12 EV POS.1
PIN 3 = PILOT 14 EV POS.2
PIN 4 = PILOT 14 EV POS.3
PIN 5 = PILOT 14 EV POS.4
PIN 6 = PILOT 12 EV POS.4
PIN 7 = PILOT 14 EV POS.5
PIN 8 = PILOT 14 EV POS.7
PIN 9 = PILOT 14 EV POS.8
PIN 10 = PILOT 14 EV POS.9
PIN 11 = PILOT 14 EV POS.10
PIN 12 = PILOT 14 EV POS.11
PIN 13 = PILOT 12 EV POS.11
PIN 14 = PILOT 14 EV POS.12
PIN 15 = PILOT 12 EV POS.12

POS.	1	2	3	4	5	6	7	8	9	10	11	12

37 PIN Connector correspondence for manifold mounted on bases for bistable valves

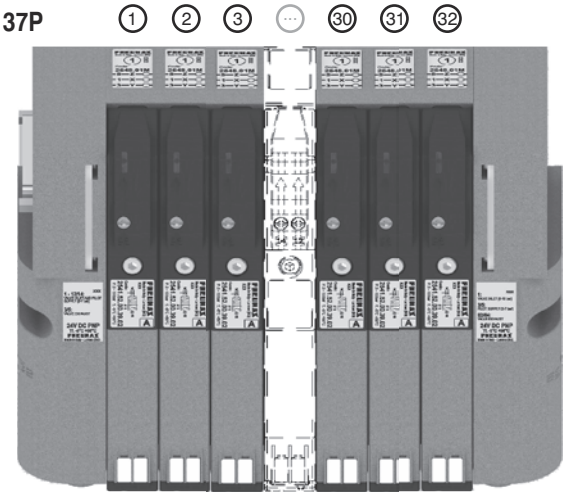


PIN 1 = PILOT 14 EV POS.1
PIN 2 = PILOT 12 EV POS.1
PIN 3 = PILOT 14 EV POS.2
PIN 4 = NOT CONNECTED
PIN 5 = PILOT 14 EV POS.3
PIN 6 = NOT CONNECTED
PIN 7 = PILOT 14 EV POS.4
PIN 8 = PILOT 12 EV POS.4
PIN 9 = PILOT 14 EV POS.5
PIN 10 = NOT CONNECTED
PIN 11 = PILOT 14 EV POS.7
PIN 12 = NOT CONNECTED
PIN 13 = PILOT 14 EV POS.8
PIN 14 = NOT CONNECTED
PIN 15 = PILOT 14 EV POS.9
PIN 16 = NOT CONNECTED
PIN 17 = PILOT 14 EV POS.10
PIN 18 = NOT CONNECTED
PIN 19 = PILOT 14 EV POS.11
PIN 20 = PILOT 12 EV POS.11
PIN 21 = PILOT 14 EV POS.12
PIN 22 = PILOT 12 EV POS.12

POS.	1	2	3	4	5	6	7	8	9	10	11	12

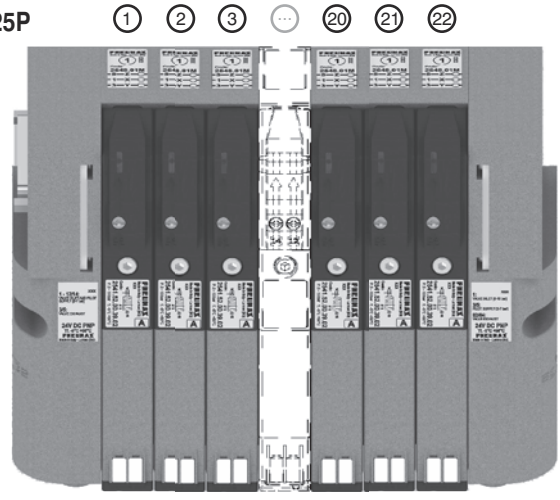
37 PIN Connector correspondence for manifold for 32 position manifold with monostable valves on base

37P



POS.	1	2	3	...	30	31	32

25P



POS.	1	2	3	...	20	21	22

2

General :

Using the 2540.03.25P output terminal it is possible to make any electrical signals not used by valves available on a 25 sub-D female connector at the right end of the manifold.
It is possible to then join a multi-core cable to link to the next manifold, or connect directly to one or two I/O modules.
The I/O modules can accept input or output signals, depending upon what is connected.

Ordering code

2540.08T

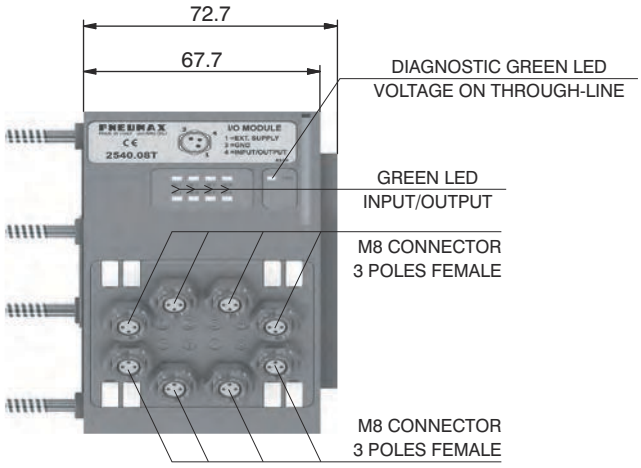
Please note: If the manifold is connected by a multi-core connection, each connection can be used as either an input or an output, while if the manifold is connected to a serial node the connections can only be used as an output.

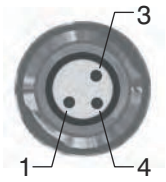
It is possible to connect the manifold to up to two I/O modules.

Each I/O module includes 8 diagnostic LEDs which indicate the presence of an Input / Output signal for each connector.

Please note: For an LED to function, a signal of at least +15VDC must be present on pin 4 of the connector. If this signal is lower, the LED will not light, this does not compromise the normal Input / Output function of the unit.

Overall dimensions and I/O layout :





PIN	DESCRIPTION
1	+24 VDC
4	INPUT/OUTPUT
3	GND

Input features:

Each connection can accept either two wire (switches, magnetic switches, pressure switches, etc.) or three wire connections (photocells, electronic end of stroke sensors, etc.) If +24VDC is required on at Pin 1 of each connector, it is possible to provide this via the through-line pin of the multi-pole connector.
I.E :
Pin 25 of the 25 pin multi-pole connector (code 2540.02.25P or 2540.12.25P)
Pin 36-37 of the 37 pin multi-pole connector (code 2540.02.37P or 2540.12.37P)

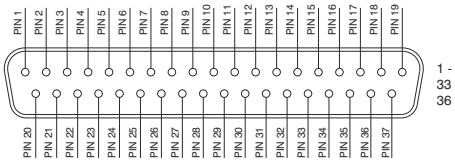
Output features:

Attention: The output connections are not protected against short-circuit. Please pay attention when wiring (avoid Pin 4 being connected to Pin 3 or Pin 1).

	Model	2540.08T
	Case	Reinforced technopolymer
General characteristics	I/O Connector	M8 connector 3 poles female (IEC 60947-5-2)
	PIN 1 voltage (connector used as Input)	By the user
	PIN 4 voltage diagnosis	Green Led
	Node consumption (Outlets excluded)	7mA per each LED with 24 VDC signal
	Outlets voltage	+23,3 VDC (serial) /by the user (multipolar)
	Input voltage	Depend by the using
	Maximum outlet current	100 mA (serial) / 400 mA (multipolar)
	Maximum Input/Output	8 per module
	Multiconnector max. Current	100 mA
	Connections to manifold	Direct connection to 25 poles connector
	Maximum n. of moduls	2
	Protection degree	IP65 when assembled
	Ambient temperature	from -0° to +50° C

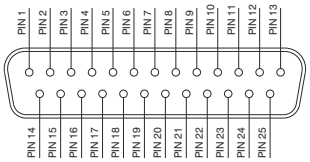
CORRESPONDENCE BETWEEN MULTI-POLE SIGNAL AND CONNECTOR

SUB-D TYPE 37 POLE MALE CONNECTOR

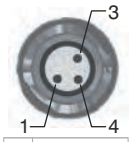


1 - 32 = SIGNALS
33 - 35 = GND
36 - 37 = THROUGH LINE

SUB-D TYPE 25 POLE MALE CONNECTOR



1 - 22 = SIGNALS
23 - 24 = GND
25 = THROUGH LINE



PIN	DESCRIPTION
1	THROUGH LINE
4	SIGNAL
3	GND

Connection modes:

The I/O module changes it is operation depending on the way the manifold is controlled. There are two possible modes:

A) Control via multi-pole connection
B) Control via fieldbus

In order to use the I/O module, the correct right hand endplate with 25 pole female outlet connector must be used.
(Code 2540.03.25P).

A) Control via multi-pole :

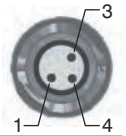
M8 connector used as Input:

Attention: Voltage applied to each connector is passed to multi-pole connector pin.

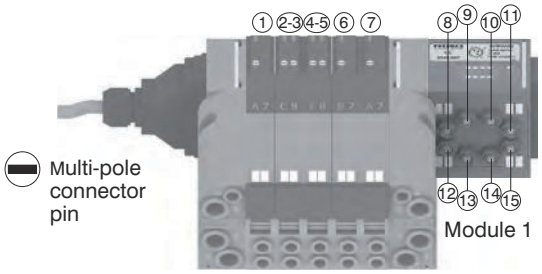
M8 connector used as Output:

Output voltage will the same as is applied at the multi-pole connector pin.
The maximum output current depends upon the power unit used, but we recommend no more than 250mA.

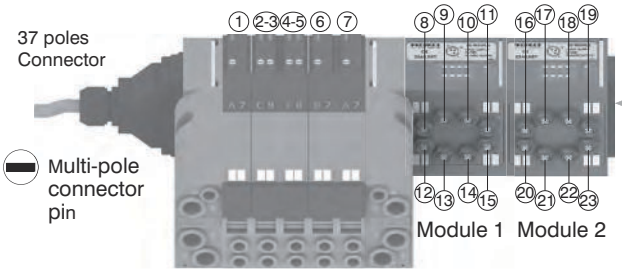
Attention: Since every cable has a degree of resistance, there will always be a voltage drop depending on the cable's length, sectional area and the current.



PIN	DESCRIPTION
1	THROUGH LINE
4	SIGNAL
3	GND

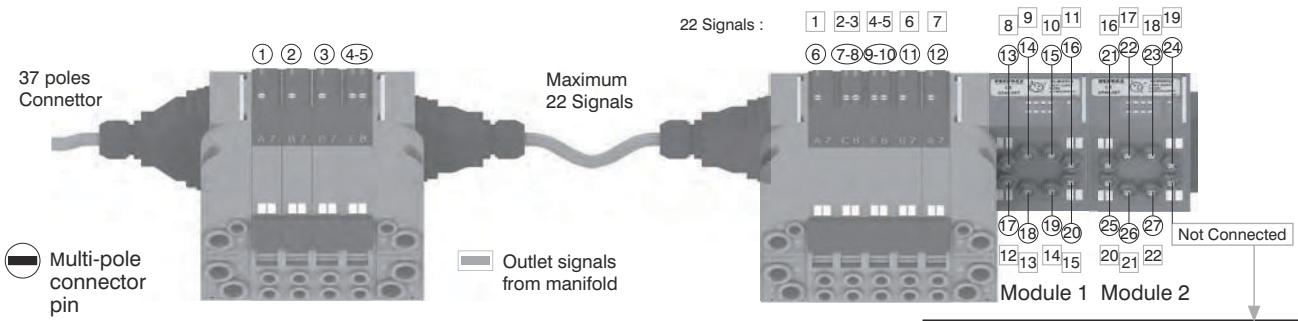


Attention:
Only one more I/O module can be added.



Attention:
No more additions are possible

Attention : Optyma 32-T solenoid valve manifolds permit up to 22 electrical signals that are not used by manifolds to be made available: these signals can be managed by another manifold and / or by I/O modules.
The I/O module will manage these unused signals. Connections that are not managing useful signals will remain unconnected.

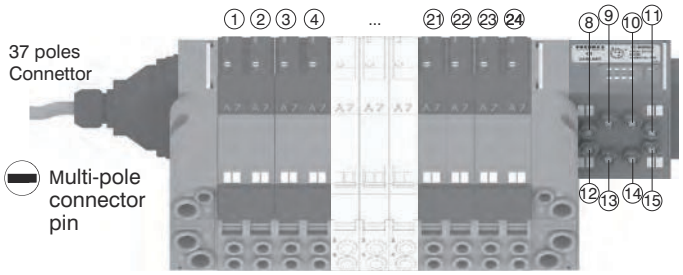


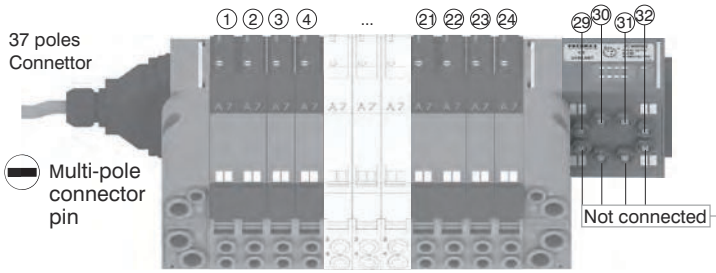
Please note: this example considers a 37 pin multi-pole connector.
The same configuration managed by a 25 pin multi-pole connector will stop at number 22 of multi-pole connector and at number 17 of the manifold. 22 17

Attention:
Signal Not connected
GND Connected
Through line Connected

2

Please note: Optyma 32-T solenoid valve manifolds manage up to 32 signals. If the manifold uses more than 24 signals the I/O module will manage only the remainder. Connections that are not managing useful signals will remain unconnected.

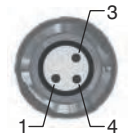




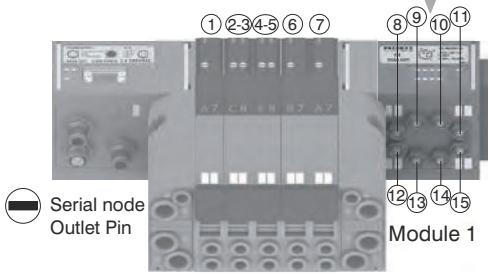
Attention:
Signal Not connected
GND Connected
Through line Connected

B) Control via fieldbus:

With this kind of control the I/O module can only be used as an output. Pin 1 of each connector is not connected. The output voltage will be 0.7V lower than that applied to Pin 4 of the connector.
The maximum output current for each output is 100mA. The correspondence between control byte and each single output depends on how many electrical signals are used by the manifold and by the relative position of the I/O module.

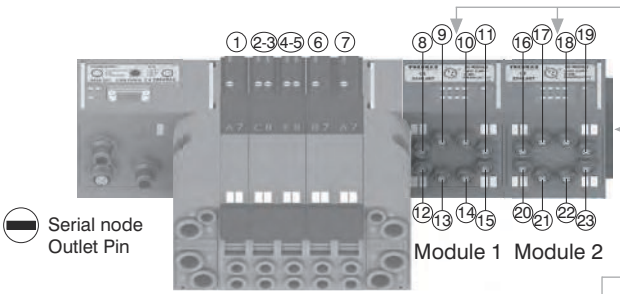


PIN	DESCRIPTION
1	NOT CONNECTED
4	SIGNAL
3	GND



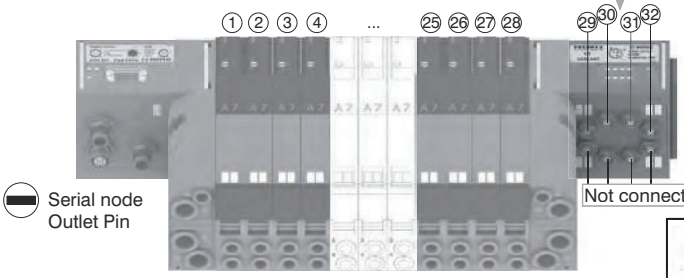
Attention:
Output only

Attention:
Only one more
I/O module
can be added.



Attention:
Output only

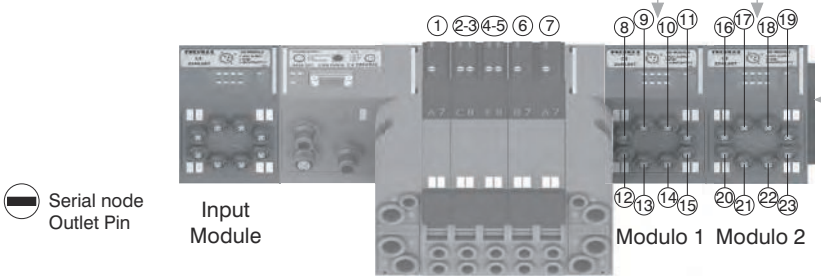
Attention:
No more additions
are possible



Attention:
Output only

Attention:
Signal Not connected
GND Connected

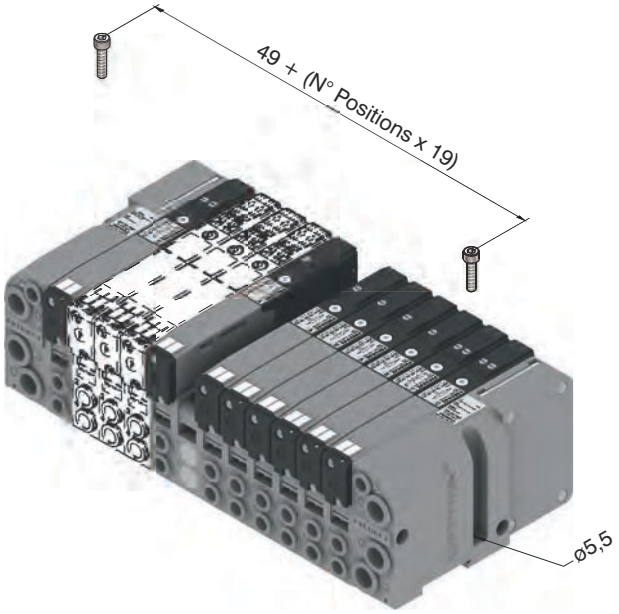
Please note: I/O modules don't allow to connect any additional valves manifold after them.

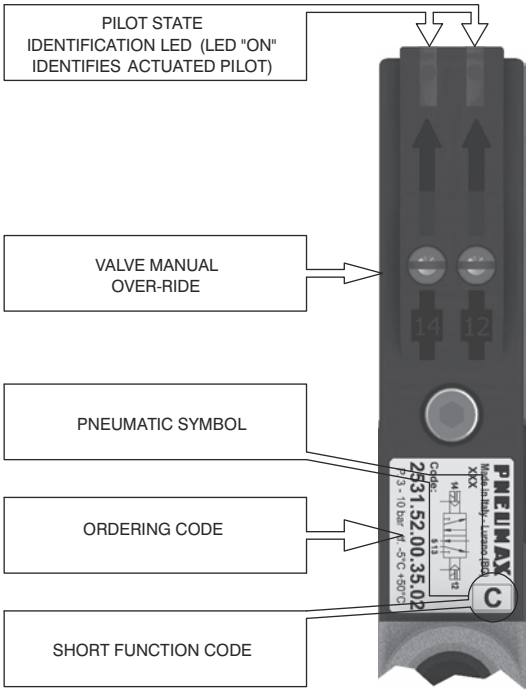


Attention:
Output only

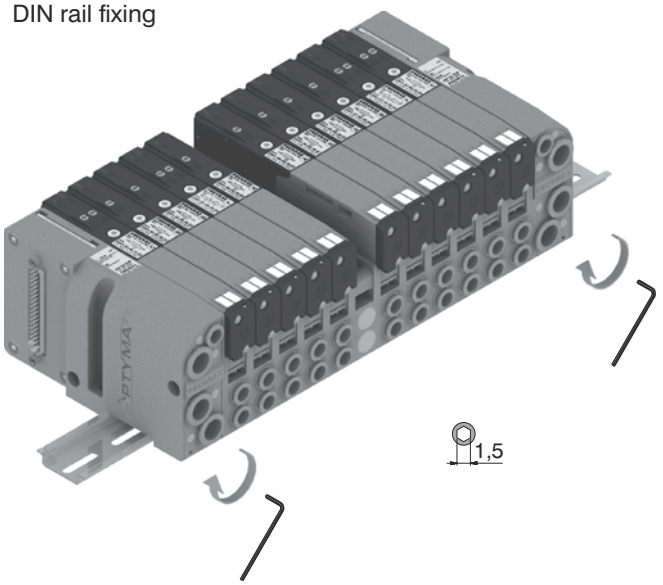
Attention:
No more additions
are possible

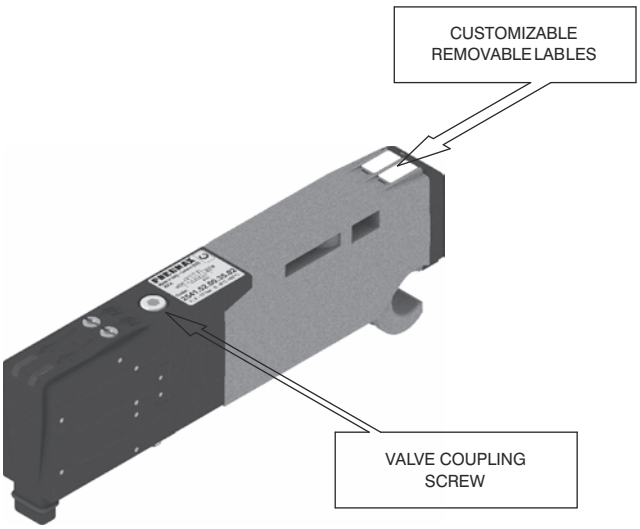
From the top



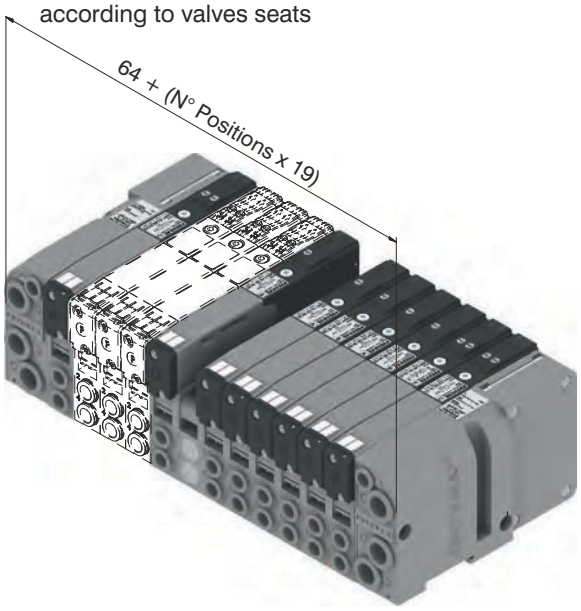


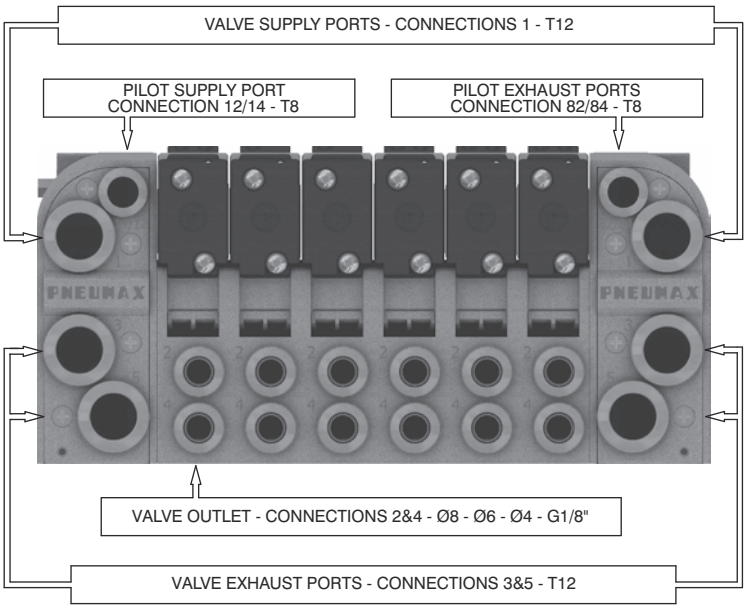
DIN rail fixing





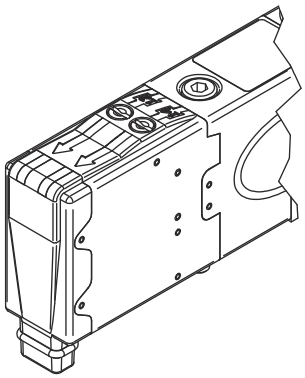
Maximum possible size
according to valves seats

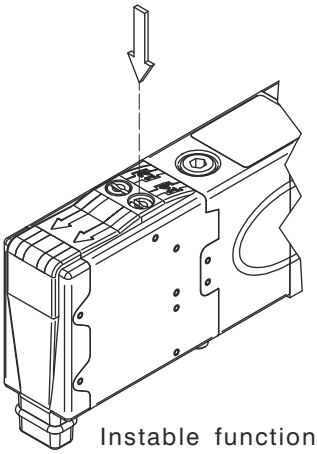




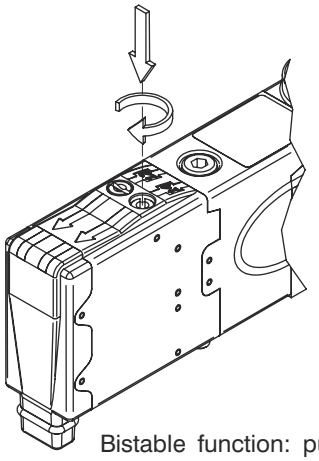
2

Manual override actuation





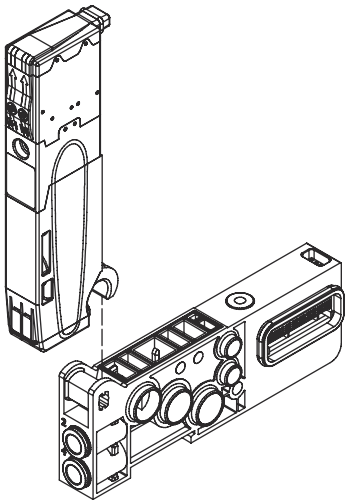
Instable function: push to actuate (when released it moves back to the original position).

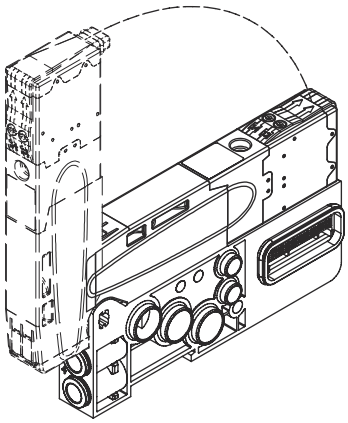


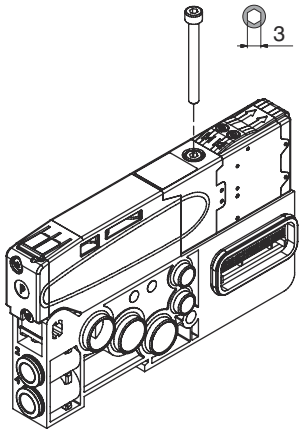
Bistable function: push and turn to get the bistable function

NOTE : It is strongly suggested to replace the original position after using

Valve Installation

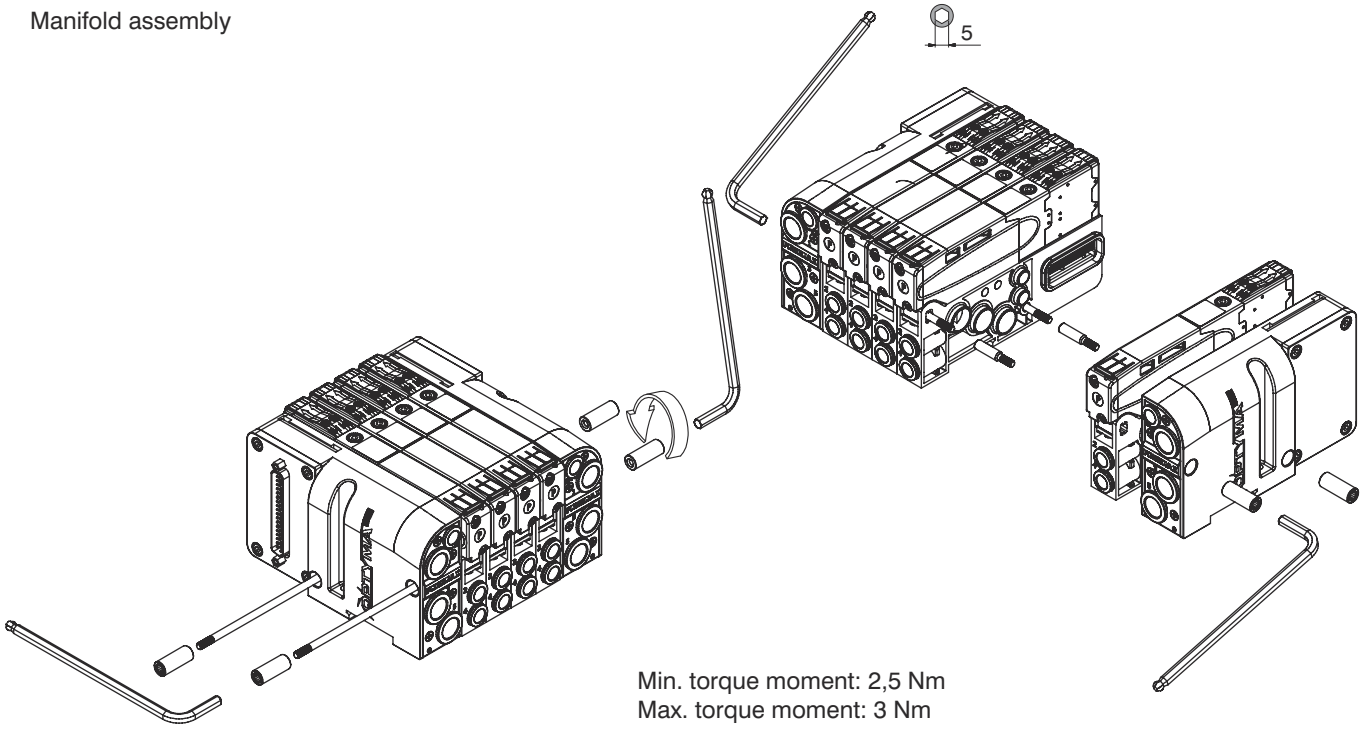






NOTE: Torque moment 1 Nm

Manifold assembly



Min. torque moment: 2,5 Nm
Max. torque moment: 3 Nm

Manifold Layout configuration

MULTIPOINT CONNECTION

MP = PNP 24 V DC
MN = NPN 24 V DC
MA = 24 V AC

LEFT ENDPLATE

A2 = 25 poles - Self feeding
A3 = 37 poles - Self feeding
E2 = 25 poles - External feeding
E3 = 37 poles - External feeding

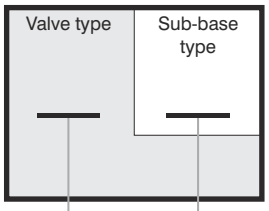
RIGHT ENDPLATE

U0 = Closed
U2 = 25 Poles
U3 = 37 Poles

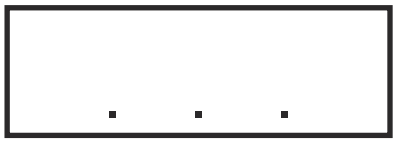
I/O MODULE

M8
(Requires 25 poles right endplate)

MODUL CONFIGURATION



ACCESSORIES CONFIGURATION



SHORT CODE FUNCTION / CONNECTION :

A1= 5/2 Sol.-Spring + BASE 1 - CARTR. G1/8" GAS
A2= 5/2 Sol.-Spring + BASE 2 - CARTR. G1/8" GAS
A3= 5/2 Sol.-Spring + BASE 1 - CARTR. Ø4
A4= 5/2 Sol.-Spring + BASE 2 - CARTR. Ø4
A5= 5/2 Sol.-Spring + BASE 1 - CARTR. Ø6
A6= 5/2 Sol.-Spring + BASE 2 - CARTR. Ø6
A7= 5/2 Sol.-Spring + BASE 1 - CARTR. Ø8
A8= 5/2 Sol.-Spring + BASE 2 - CARTR. Ø8
B1= 5/2 Sol.-Diff. + BASE 1 - CARTR. G1/8" GAS
B2= 5/2 Sol.-Diff. + BASE 2 - CARTR. G1/8" GAS
B3= 5/2 Sol.-Diff. + BASE 1 - CARTR. Ø4
B4= 5/2 Sol.-Diff. + BASE 2 - CARTR. Ø4
B5= 5/2 Sol.-Diff. + BASE 1 - CARTR. Ø6
B6= 5/2 Sol.-Diff. + BASE 2 - CARTR. Ø6
B7= 5/2 Sol.-Diff. + BASE 1 - CARTR. Ø8
B8= 5/2 Sol.-Diff. + BASE 2 - CARTR. Ø8
C2= 5/2 Sol.-Sol. + BASE 2 - CARTR. G1/8" GAS
C4= 5/2 Sol.-Sol. + BASE 2 - CARTR. Ø4
C6= 5/2 Sol.-Sol. + BASE 2 - CARTR. Ø6
C8= 5/2 Sol.-Sol. + BASE 2 - CARTR. Ø8
E2= 5/3 CC Sol.-Sol. + BASE 2 - CARTR. G1/8" GAS
E4= 5/3 CC Sol.-Sol. + BASE 2 - CARTR. Ø4
E6= 5/3 CC Sol.-Sol. + BASE 2 - CARTR. Ø6
E8= 5/3 CC Sol.-Sol. + BASE 2 - CARTR. Ø8

F2= 2x3/2 NC-NC (= 5/3 OC) Sol.-Sol. + BASE 2 - CARTR. G1/8" GAS
F4= 2x3/2 NC-NC (= 5/3 OC) Sol.-Sol. + BASE 2 - CARTR. Ø4
F6= 2x3/2 NC-NC (= 5/3 OC) Sol.-Sol. + BASE 2 - CARTR. Ø6
F8= 2x3/2 NC-NC (= 5/3 OC) Sol.-Sol. + BASE 2 - CARTR. Ø8
G2= 2x3/2 NO-NO (= 5/3 PC) Sol.-Sol. + BASE 2 - CARTR. G1/8" GAS
G4= 2x3/2 NO-NO (= 5/3 PC) Sol.-Sol. + BASE 2 - CARTR. Ø4
G6= 2x3/2 NO-NO (= 5/3 PC) Sol.-Sol. + BASE 2 - CARTR. Ø6
G8= 2x3/2 NO-NO (= 5/3 PC) Sol.-Sol. + BASE 2 - CARTR. Ø8
H2= 2x3/2 NC-NO Sol.-Sol. + BASE 2 - CARTR. G1/8" GAS
H4= 2x3/2 NC-NO Sol.-Sol. + BASE 2 - CARTR. Ø4
H6= 2x3/2 NC-NO Sol.-Sol. + BASE 2 - CARTR. Ø6
H8= 2x3/2 NC-NO Sol.-Sol. + BASE 2 - CARTR. Ø8
I2= 2x3/2 NO-NC Sol.-Sol. + BASE 2 - CARTR. G1/8" GAS
I4= 2x3/2 NO-NC Sol.-Sol. + BASE 2 - CARTR. Ø4
I6= 2x3/2 NO-NC Sol.-Sol. + BASE 2 - CARTR. Ø6
I8= 2x3/2 NO-NC Sol.-Sol. + BASE 2 - CARTR. Ø8
T1= Free valve space plug + BASE 1 - CARTR. G1/8" GAS
T2= Free valve space plug + BASE 2 - CARTR. G1/8" GAS
T3= Free valve space plug + BASE 1 - CARTR. Ø4
T4= Free valve space plug + BASE 2 - CARTR. Ø4
T5= Free valve space plug + BASE 1 - CARTR. Ø6
T6= Free valve space plug + BASE 2 - CARTR. Ø6
T7= Free valve space plug + BASE 1 - CARTR. Ø8
T8= Free valve space plug + BASE 2 - CARTR. Ø8

NOTE:

While configuring the manifold always be careful that the maximum number of electrical signals available is 32.
The use of monostable valve mounted on a base type 2 (2 electrical signals occupied) causes the loss of one electric signal. In this case the monostable valve can be replaced by a bistable valve. The diaphragms plugs are used to intercept the conduits 1,3 & 5 of the base. If it is necessary to interrupt more than one conduit in the same time then put in line the letters which identifies the position (for exemple : regarding the 3 & 5 conduits, put the Y & Z letters).
Should one or more conduits be cut more than one time it is necessary to add the relevant intermediate Supply/Exhaust module.

ACCESSORIES

U2 = Power supply 2 positions module
U4 = Power supply 4 positions module
W = Intermediate supply & exhaust module
X = Diaphragm plug on pipe 1
Y = Diaphragm plug on pipe 3
Z = Diaphragm plug on pipe 5
XY = Diaphragm plug on pipe 1 & 3
ZX = Diaphragm plug on pipe 5 & 1
ZY = Diaphragm plug on pipe 5 & 3
ZXY = Diaphragm plug on pipe 5, 1 & 3

Series 2500 OPTYMA-T solenoid valve manifolds managed by multipoint connection are "well tried components"

	Well-tried component	- The product is a well-tried product for a safety-related application according to ISO 13849-1. - The relevant basic and well-tried safety principles according ISO 13849-2 for this product are fulfilled. - The suitability of the product for a precise application must be verified and confirmed by the user.
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