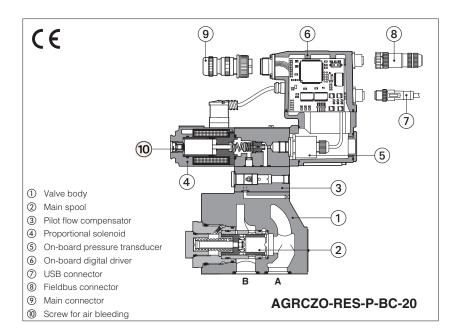


Proportional reducing valves high performance

piloted, with on-board pressure transducer



AGRCZO-R, AGRCZO-REB, AGRCZO-RES

Piloted, digital proportional reducing valves with integral pressure transducer for pressure closed loop controls.

R without on-board digital driver, to be coupled with separated driver.

REB basic execution, with on-board digital driver, analog reference signals and USB port for software functional parameters setting.

RES full execution, with on-board digital driver which includes also fieldbus interface for functional parameters setting, reference signals and real-time diagnostics.

Seals material,

see section 11

Series number

P = with integral mechanical pressure limiter R = with integral check valve for free reverse flow Electronics options, only for REB and RES (4):

(omit for std voltage 0÷10 VDC)

signals - 12 pin connector

= current reference input and monitor 4÷20 mA

Z = double power supply, enable, fault and monitor

Hydraulic options (4):

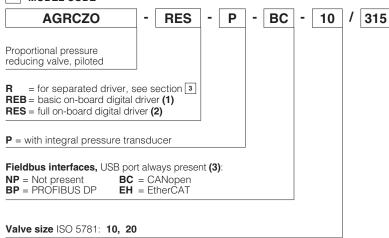
= enable signal

= NBR PE = FKM

BT = NBR low temp.

Size: 10 and 20 - ISO 5781 Max flow: 160 and 300 I/min Max pressure: 350 bar

1 MODEL CODE



Max regulated pressure:

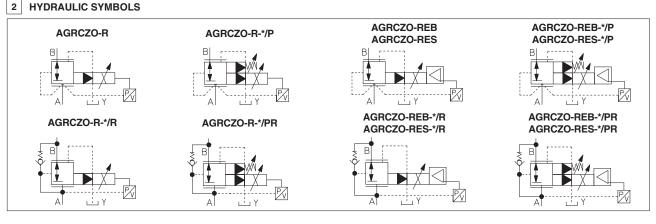
100 = 100 bar **210** = 210 bar **315** = 315 bar **350** = 350 bar

(1) Only for NP

(4) For possible combined options, see section 15

(3) Omit for R execution

(2) Only for BC, BP, EH



3 OFF-BOARD ELECTRONIC DRIVER - only for R

Drivers model	E-BM-RES	
Туре	Digital	
Format	DIN rail panel format	
Tech table	GS203	

4 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FS900** and in the user manuals included in the E-SW-* programming software.

5 VALVE SETTINGS AND PROGRAMMING TOOLS

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **FS900**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

 E-SW-BASIC
 support
 NP (USB)
 PS (Serial)
 IR (Infrared)

 E-SW-FIELDBUS
 support
 BC (CANopen)
 BP (PROFIBUS DP)
 EH (EtherCAT)

 E-SW-*/PQ
 EW (POWERLINK)
 EI (EtherNet/IP)
 EP (PROFINET)

 E-SW-*/PQ
 support
 valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

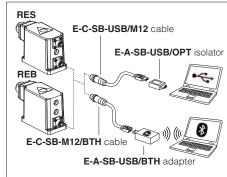
<u>^</u>

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection



WARNING: see tech table **GS500** for the list of countries where the Bluetooth adapter, has been approved

USB or Bluetooth connection



6 SMART TUNING

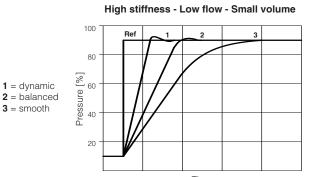
Smart tuning allows to adjust the valve dynamic response in order to match different hydraulic conditions and performance requirements.

The valve is provided with 3 factory settings for the pressure control:

- dynamic fast response time for best dynamic performances. Default factory setting for pressure valves
- balanced average response time suitable for major applications
- smooth attenuated response time for slow regulation without overshoots

Smart tuning setting can be switched from Dynamic (default) to Balanced or Smooth via software or fieldbus; if requested, performances can be further customized directly tuning each single control parameter. For details consult related manuals E-MAN-RI-* and Quickstart, see section [21].

Below indications have to be considered as a general guideline, being affected by hydraulic circuit stiffness, working flow and dead volume.





7 | FIELDBUS - only for RES, see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These execution allow to operate the valves through fieldbus or analog signals available on the main connector.

8 GENERAL CHARACTERISTICS

Assembly position	Any position		
Subplate surface finishing to ISO 4401	Acceptable roughness index: Ra ≤ 0,8, recommended Ra 0,4 – Flatness ratio 0,01/100		
MTTFd valves according to EN ISO 13849	75 years, see technical table P007		
Ambient temperature range	R: Standard = -20° C ÷ $+70^{\circ}$ C /PE option = -20° C ÷ $+70^{\circ}$ C /BT option = -40° C ÷ $+60^{\circ}$ C REB, RES: Standard = -20° C ÷ $+60^{\circ}$ C /PE option = -20° C ÷ $+60^{\circ}$ C /BT option = -40° C ÷ $+60^{\circ}$ C		
Storage temperature range	R: Standard = -20° C ÷ $+80^{\circ}$ C /PE option = -20° C ÷ $+80^{\circ}$ C /BT option = -40° C ÷ $+70^{\circ}$ C REB, RES: Standard = -20° C ÷ $+70^{\circ}$ C /PE option = -20° C ÷ $+70^{\circ}$ C /BT option = -40° C ÷ $+70^{\circ}$ C		
Surface protection	Zinc coating with black passivation, galvanic treatment (driver housing for REB and RES)		
Corrosion resistance	Salt spray test (EN ISO 9227) > 200 h		
Compliance	CE according to EMC directive 2014/30/EU (Immunity: EN 61000-6-2; Emission: EN 61000-6-3) RoHS Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006		

9 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		AGRCZO-*-10	AGRCZO-*-20
Max regulated pressure	[bar]	100; 210;	315; 350
Min regulated pressure	[bar]	1; 3 (only	for /350)
Max pressure at port A or B	[bar]	35	50
Max pressure at port Y	[bar]	pilot drain always external, to be direc	tly connected to tank at zero pressure
Max flow	[l/min]	160	300
Response time 0-100% step signal (depending on installation) (1) [ms]		≤ 45	≤50
Hysteresis		≤ 0,5 [% of m	ax pressure]
Linearity		≤ 1,0 [% of max pressure]	
Repeatability		≤0,2 [% of max pressure]	
Thermal drift		zero point displacement < 1% at ΔT = 40°C	

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 3

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response, see section 6

10 ELECTRICAL CHARACTERISTICS

		(ripple max 10 % VPP)	
R = 30 W REB , RES = 50 W			
2,6 A			
3 ÷ 3,3 Ω			
0	'	Input impedance Input impedance	
0	0		ce
Range: 0 ÷ 9 VDC (OFF s	state), 15 ÷ 24 VDC (ON s	state), 9 ÷ 15 VDC (not ac	cepted); Input impedance: Ri > 87 k Ω
Output range: 0 ÷ 24 VDC (ON state \cong VL+ [logic power supply]; OFF state \cong 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)			
E-ATR-8/*/I Output signal: 4 ÷ 20 mA (see tech table GS465)			
Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, current control monitoring, power supplies level, pressure transducer failure			
H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account			
R = IP65; REB, RES = IP66 / IP67 with mating connectors			
Continuous rating (ED=	:100%)		
Tropical coating on ele	ctronics PCB		
Short circuit protection of solenoid's current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply			
USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT EC 61158
	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX
LiYCY shielded cables	, see section 19		
	Rectified and filtered R = 30 W 2,6 A 3 ÷ 3,3 Ω Voltage: range ±10 V Current: range ±20 m Voltage: maximum ran Current: maximum ran Range: 0 ÷ 9 VDC (OFF: Output range : 0 ÷ 24 external negative volta E-ATR-8/*/I Output: Solenoid not connected current control monitor H (180°) Due to the och the European standard R = IP65; REB, RES = Continuous rating (ED= Tropical coating on election protection against reveal USB Atos ASCII coding not insulated USB 2.0 + USB OTG	Rectified and filtered: VRMS = 20 ÷ 32 VMAX R = 30 W REB, RES = 50 W 2,6 A 3 ÷ 3,3 Ω Voltage: range ±10 VDC (24 VMAX tollerant) Current: range ±20 mA Voltage: maximum range 0 ÷ 10 VDC Current: maximum range 0 ÷ 20 mA Range: 0 ÷ 9 VDC (OFF state), 15 ÷ 24 VDC (ON state) Output range: 0 ÷ 24 VDC (ON state) = VL+ external negative voltage not allowed (e.g. du E-ATR-8/*/I Output signal: 4 ÷ 20 mA (se Solenoid not connected/short circuit, cable br current control monitoring, power supplies lev H (180°) Due to the occuring surface tempera the European standards ISO 13732-1 and ENs R = IP65; REB, RES = IP66 / IP67 with mating Continuous rating (ED=100%) Tropical coating on electronics PCB Short circuit protection of solenoid's current su protection against reverse polarity of power su USB Atos ASCII coding not insulated	Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP) R = 30 W REB, RES = 50 W 2,6 A 3 ÷ 3,3 Ω Voltage: range ±10 VDC (24 VMAX tollerant) Input impedance Voltage: maximum range 0 ÷ 10 VDC @ max 5 mA Current: maximum range 0 ÷ 20 mA @ max 500 Ω load resistance Range: 0 ÷ 9 VDC (OFF state), 15 ÷ 24 VDC (ON state), 9 ÷ 15 VDC (not accompany of the VDC (ON state), 9 ÷ 15 VDC (Not accompany of the VDC (ON state), 9 ÷ 15 VDC (Not accompany of the VDC (ON state),

- (1) In case of pressure transducer failure, the valve's reaction can be configured through Atos E-SW software to:
 - cut off the current to solenoid, therefore the regulated pressure will be reduced to minimum value (default setting)
 - automatically switch the pressure control from closed loop (dynamic, balaced, smooth) to open loop, to let the valve to temporarily operate with reduced regulation accuracy

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 Vpc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

11 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	l temperature	FKM seals (/PE option) = -20°C	+60°C (+80°C for R), with HFC h ÷ +80°C n) = -40°C ÷ +60°C, with HFC hyc	•
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s		
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	www.atos.com or KTF catalog
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard
Mineral oils		NBR, FKM, NBR low temp.	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922
Flame resistant with water		NBR, NBR low temp.	HFC	150 12922



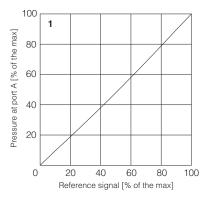
12 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

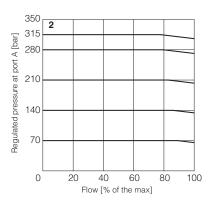
1 Regulation diagrams

with flow rate Q = 10 l/min

2 Pressure/flow diagrams

with reference pressure set with Q = 10 l/min





3-6 Pressure drop/flow diagrams

with zero reference signal

Differential pressure B→A

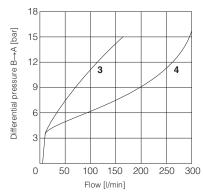
3 = AGRCZO-*-10

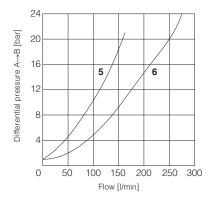
4 = AGRCZO-*-20

Differential pressure A→B (through check valve)

 $5 = AGRCZO^{-*}-10/*/R$

6 = AGRCZO-*-20/*/R





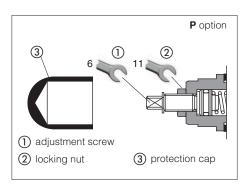
13 HYDRAULIC OPTIONS

P = This option provides a mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

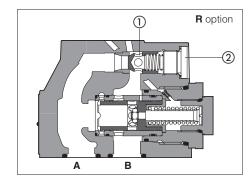
At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded
- turn clockwise the adjustment screw ① until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal
- turn clockwise the adjustment screw ① of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working



- R = This option provides a integral check valve for free reverse flow A→B
 - ① Check valve cracking pressure = 0,5 bar
 - ② Plug



14 ELECTRONICS OPTIONS - only for REB and RES

I = This option provides 4 ÷ 20 mA current reference and monitor signals, instead of the standard 0 ÷ 10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.
It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected.

Q = This option permits to inhibit the valve function without removing the power supply to the driver. Upon disable command the current to the solenoid is zeroed and the valve's spool moves to rest position.

The option /Q is suggested for all cases where the valve has to be frequently inhibited during the machine cycle – see 17.5 for signal specifications.

 ${f Z}={f This}$ option provides, on the 12 pin main connector, the following additional features:

by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

Fault output signal - see 17.6

Enable input signal - see above option /Q

Power supply for driver's logics and communication - see 17.2



15 POSSIBLE COMBINED OPTIONS

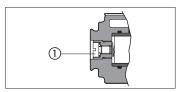
for R: /PR

for REB and RES: /IP, /IQ, /IR, /IZ, /PQ, /PR, /PZ, /QR, /RZ, /IPQ, /IPR, /IPZ, /IQR, /IRZ, /PQR, /PRZ, /IPQR, /IPRZ

16 AIR BLEEDING

At the first valve commissioning the air eventually trapped inside the solenoid must be bled-off though the screw \odot located at the rear side of the solenoid housing.

The presence of air may cause pressure instability and vibrations.



17 POWER SUPPLY AND SIGNALS SPECIFICATIONS - only for REB and RES

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

17.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. In case of separate power supply see 17.2.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

17.2 Power supply for driver's logic and communication (VL+ and VL0) - only for /Z

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 9 and 10, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

17.3 Pressure reference input signal (P_INPUT+)

The driver controls in closed loop the current to the valve pressure proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDc for standard and $4 \div 20$ mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Drivers with fieldbus interface (BC, BP, EH) can be software set to receive reference signal directly by the machine control unit (fieldbus reference).

Analog reference input signal can be used as on-off commands with input range 0 ÷ 24 VDC.

17.4 Pressure monitor output signal (P_MONITOR)

The driver generates an analog output signal proportional to the actual pressure of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, defaults settings are $0 \div 10$ VDc for standard and $4 \div 20$ mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of $0 \div 10$ VDc or $0 \div 20$ mA.

17.5 Enable input signal (ENABLE) - not for standard

To enable the driver, supply a 24 Vpc on pin 3 (pin C): Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

17.6 Fault output signal (FAULT) - only for $\ensuremath{\text{/Z}}$ option

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal broken for $4 \div 20$ mA input, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC.

Fault status is not affected by the Enable input signal.



18 ELECTRONIC CONNECTIONS

18.1 Main connector signals - 7 pin (A1) Standard and /Q option - for REB and RES

PIN	Standard	/Q	TECHNICAL SPECIFICATIONS	NOTES
Α	V+		Power supply 24 Vbc	Input - power supply
В	V0		Power supply 0 Vpc	Gnd - power supply
С	AGND		Analog ground	Gnd - analog signal
		ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver, referred to V0	Input - on/off signal
D	P_INPUT+		Pressure reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
Е	INPUT-		Negative reference input signal for P_INPUT+	Input - analog signal
F	P_MONITOR AGND	referred to: V0	Pressure monitor output signal: $0 \div 10 \text{ Vpc}$ / $0 \div 20 \text{ mA}$ maximum range Defaults are $0 \div 10 \text{ Vpc}$ for standard and $4 \div 20 \text{ mA}$ for /I option	Output - analog signal Software selectable
G	EARTH		Internally connected to driver housing	

18.2 Main connector signals - 12 pin (A2) /Z option - for REB and RES

PIN	/Z	TECHNICAL SPECIFICATIONS	NOTES
1	V+	Power supply 24 Vpc	Input - power supply
2	V0	Power supply 0 Vpc	Gnd - power supply
3	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver, referred to VL0	Input - on/off signal
4	P_INPUT+	Pressure reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
5	INPUT-	Negative reference input signal for P_INPUT+	Input - analog signal
6	P_MONITOR	Pressure monitor output signal: $0 \div 10 \text{ Vpc}$ / $0 \div 20 \text{ mA}$ maximum range, referred to VL0 Defaults are $0 \div 10 \text{ Vpc}$ for standard and $4 \div 20 \text{ mA}$ for /I option	Output - analog signal Software selectable
7	NC	Do not connect	
8	NC	Do not connect	
9	VL+	Power supply 24 Vpc for driver's logic and communication	Input - power supply
10	VL0	Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
11	FAULT	Fault (0 Vpc) or normal working (24 Vpc), referred to VL0	Output - on/off signal
PE	EARTH	Internally connected to driver housing	

Note: do not disconnect VL0 before VL+ when the driver is connected to PC USB port

18.3 Communication connectors - for REB (B) and RES (B) - (C)

В	B USB connector - M12 - 5 pin always present		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)	
1	+5V_USB	Power supply	
2	ID	Identification	
3	GND_USB	Signal zero data line	
4	D-	Data line -	
5	D+	Data line +	

©2	BP fieldbus execution, connector - M12 - 5 pin (2)		
PIN	SIGNAL TECHNICAL SPECIFICATION (1)		
1	+5V	Termination supply signal	
2	LINE-A	Bus line (high)	
3	DGND	Data line and termination signal zero	
4	LINE-B	Bus line (low)	
5	SHIELD		

(1) Shield connection on connector's housing is recommended

BC fieldbus execution, connector - M12 - 5 pin (2) PIN SIGNAL TECHNICAL SPECIFICATION (1) 1 CAN_SHLD Shield 2 NC do not connect 3 CAN_GND Signal zero data line 4 CAN_H Bus line (high) 5 CAN_L Bus line (low)

©3	©3 ©4 EH fieldbus execution, connector - M12 - 4 pin (2)			
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)		
1	TX+	Transmitter		
2	RX+	Receiver		
3	TX-	Transmitter		
4	RX-	Receiver		
Housing	SHIELD			

(2) Only for RES execution

18.4 Solenoid connection - only for R

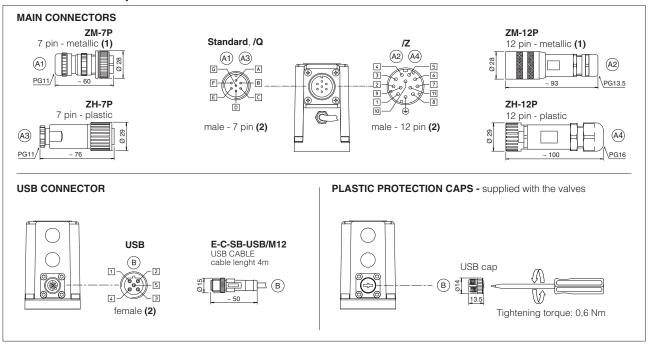
Р	IN	SIGNAL	TECHNICAL SPECIFICATION	Connector code 666	6
	1	COIL	Power supply	250	
2	2	COIL	Power supply		
(3	GND	Ground		

18.5 Pressure transducer connection - only for R

		,	
PIN	SIGNAL	TECHNICAL SPECIFICATION	Connector code ZBE-08
1	V+	Power supply	
2	NC	Not connected	2 0 0
3	TR	Output signal 4 ÷ 20 mA	3 4
4	NC	Not connected	1
5	NC	Not connected	

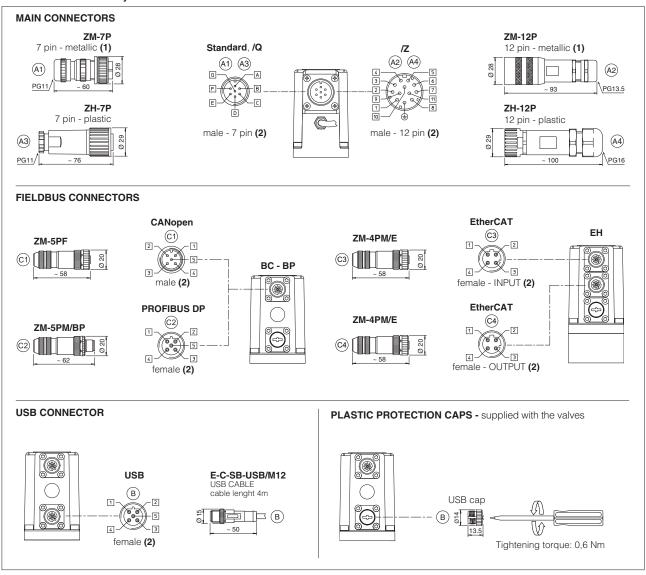


18.6 REB connections layout



(1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements (2) Pin layout always referred to driver's view

18.7 RES connections layout



(1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements (2) Pin layout always referred to driver's view

19 CONNECTORS CHARACTERISTICS - to be ordered separately

19.1 Main connectors - 7 pin - for REB and RES

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY		
CODE	A1 ZM-7P	A3 ZH-7P		
Туре	7pin female straight circular	7pin female straight circular		
Standard	According to MIL-C-5015	According to MIL-C-5015		
Material	Metallic	Plastic reinforced with fiber glass		
Cable gland	PG11	PG11		
Recommended cable	LiYCY 7 x 0,75 mm ² max 20 m (logic and power supply) or LiYCY 7 x 1 mm ² max 40 m (logic and power supply)	LiYCY 7 x 0,75 mm ² max 20 m (logic and power supply) or LiYCY 7 x 1 mm ² max 40 m (logic and power supply)		
Conductor size	up to 1 mm ² - available for 7 wires	up to 1 mm ² - available for 7 wires		
Connection type	nection type to solder to solder			
Protection (EN 60529)	IP 67	IP 67		

19.2 Main connectors - 12 pin - for REB and RES

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY		
CODE	(A2) ZM-12P	(A4) ZH-12P		
Туре	12pin female straight circular	12pin female straight circular		
Standard	DIN 43651	DIN 43651		
Material	Metallic	Plastic reinforced with fiber glass		
Cable gland	PG13,5	PG16		
Recommended cable	LiYCY 12 x 0,75 mm ² max 20 m (logic and power supply)	LiYCY 10 x 0,14mm² max 40 m (logic) LiYY 3 x 1mm² max 40 m (power supply)		
Conductor size	0,5 mm² to 1,5 mm² - available for 12 wires	0,14 mm² to 0,5 mm² - available for 9 wires 0,5 mm² to 1,5 mm² - available for 3 wires		
Connection type	to crimp	to crimp		
Protection (EN 60529)	IP 67	IP 67		

19.3 Fieldbus communication connectors - only for RES

CONNECTOR TYPE	BC CAN	open (1)	BP PROFIBUS DP (1)		EH EtherCAT (2)	
CODE	C1 ZM-5PF	©2 ZM-5PM	C1 ZM-5PF/BP	©2 ZM-5PM/BP	C1 C2	ZM-4PM/E
Туре	5 pin female straight circular	5 pin male straight circular	5 pin female straight circular	5 pin male straight circular		4 pin male straight circular
Standard	M12 coding A –	IEC 61076-2-101	M12 coding B – IEC 61076-2-101		M12 co	ding D – IEC 61076-2-101
Material	Me	tallic	Me	tallic	Metallic	
Cable gland	Pressure nut - cab	le diameter 6÷8 mm	Pressure nut - cable diameter 6÷8 mm		Pressure nut - cable diameter 4÷8 mm	
Cable	CANbus Stand	dard (DR 303-1)	PROFIBUS DP Standard		Ethernet standard CAT-5	
Connection type	screw	screw terminal		screw terminal		terminal block
Protection (EN 60529)	IF	P67	IP 67			IP 67

⁽¹⁾ E-TRM-** terminators can be ordered separately - see tech table $\ensuremath{\mathbf{GS500}}$

(2) Internally terminated

20 FASTENING BOLTS AND SEALS

	AGRCZO-*-10	AGRCZO-*-20
©	Fastening bolts:	Fastening bolts:
	4 socket head screws M10x45 class 12.9	4 socket head screws M10x45 class 12.9
	Tightening torque = 70 Nm	Tightening torque = 70 Nm
U		
	Seals:	Seals:
	2 OR 3068	2 OR 4100
()	Diameter of ports A, B: Ø 14 mm	Diameter of ports A, B: Ø 22 mm
	2 OR 109/70	2 OR 109/70
	Diameter of port X, Y: Ø 5 mm	Diameter of port X, Y: Ø 5 mm

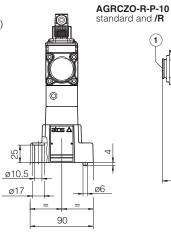
21 RELATED DOCUMENTATION

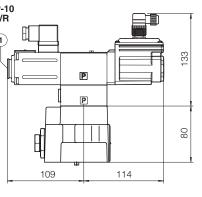
FS001	Basics for digital electrohydraulics	P005	Mounting	surfaces for electrohydraulic valves
FS900	Operating and maintenance information for proportional valves	QB400	Quickstar	t for REB valves commissioning
GS203	E-BM-RES digital driver	QF400	Quickstar	t for RES valves commissioning
GS500	Programming tools	E-MAN-	BM-RES	RES user manual (off-board)
GS510	Fieldbus	E-MAN-	RI-REB	REB user manual
K800	Electric and electronic connectors	E-MAN-	RI-RES	RES user manual

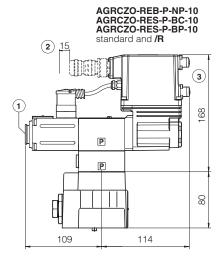


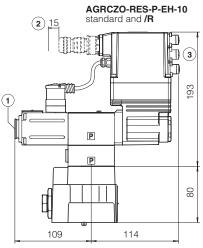
ISO 5781: 2000 Mounting surface: 5781-06-07-0-00 (see table P005)

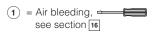
	Mass [kg]				
	R	REB, RES	RES-EH		
AGRCZO-*-10	5,8	6,3	6,4		
Option /P	+0,5				











- (2) = Space to remove the connectors
- (3) = The dimensions of all connectors must be considered, see section 18.6 and 18.7

