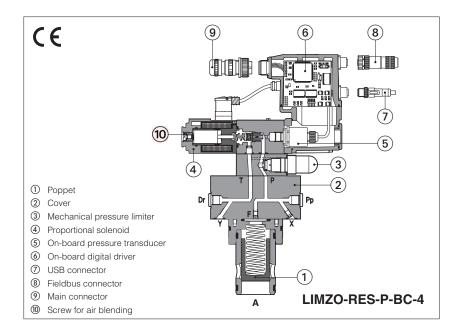


Digital proportional pressure cartridges high performance

piloted, with on-board pressure transducer - compensator, relief, reducing functions



LICZO, LIMZO, LIRZO

2-way digital proportional cartridges with on-board pressure transducer, respectively performing: pressure compensator, relief and reducing closed loop functions.

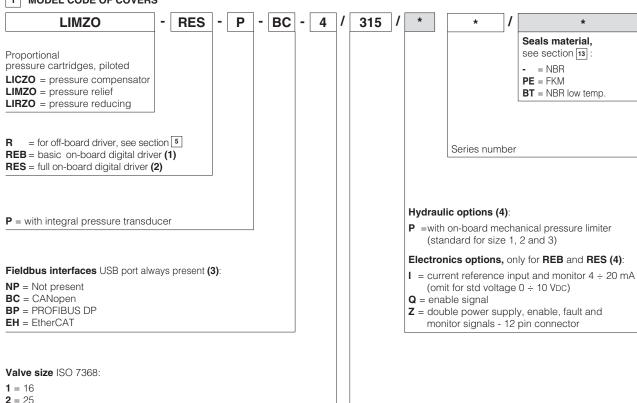
R to be coupled with off-board drivers.

REB basic execution, with on-board digital driver, analog reference signals and USB port for software functional parameters setting.

RES full execution, with on-board digital driver which includes also fieldbus interface for functional parameters setting, reference signals and real-time diagnostics.

Size: **16** ÷ **80** - ISO 7368 Max flow: up to **4500 I/min** Max pressure: **350 bar**

1 MODEL CODE OF COVERS



(1) Only for NP

3 = 32 **4** = 40

(2) Only for BC, BP, EH

5 = 50 (not for LIRZO)

6 = 63 (only for LIMZO)

8 = 80 (only for LIMZO)

(3) Omit for R execution

(4) For possible combined options, see section 17

Max regulated pressure

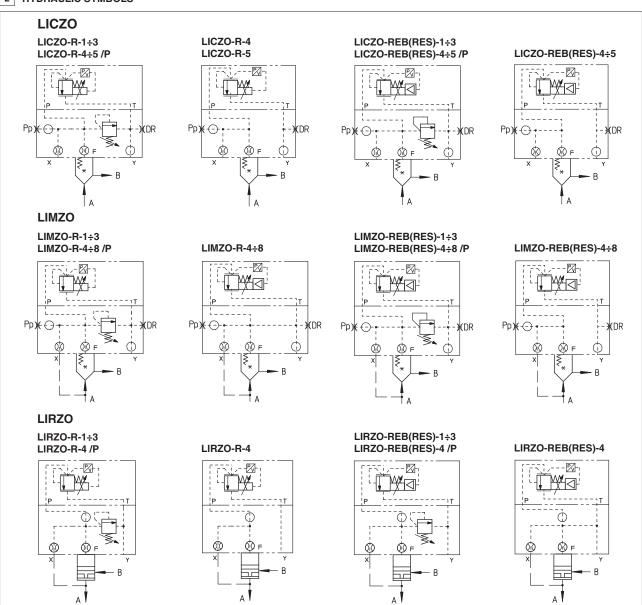
100 = 100 bar

210 = 210 bar

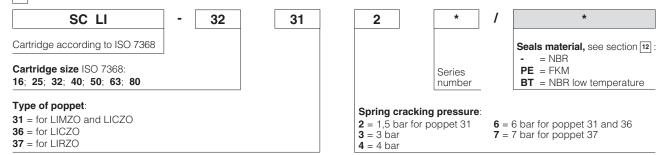
315 = 315 bar

350 = 350 bar

2 HYDRAULIC SYMBOLS



3 MODEL CODE OF CARTRIDGES



4 TYPE OF POPPET

Type of poppet	31	36	37
Functional sketch (Hydraulic symbol)	AP B B	AP B A	AP B A
Typical section			
Area ratio A: AP	1:1	1:1	1:1

5 OFF-BOARD ELECTRONIC DRIVER - only for R

Drivers model	E-BM-RES
Туре	Digital
Format	DIN rail panel format
Tech table	GS203

6 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FS900** and in the user manuals included in the E-SW-* programming software.

7 VALVE SETTINGS AND PROGRAMMING TOOLS

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **FS900**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

 E-SW-BASIC
 support:
 NP (USB)
 PS (Serial)
 IR (Infrared)

 E-SW-FIELDBUS
 support:
 BC (CANopen)
 BP (PROFIBUS DP)
 EH (EtherCAT)

 EW (POWERLINK)
 EI (EtherNet/IP)
 EP (PROFINET)

E-SW-*/PQ support: valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

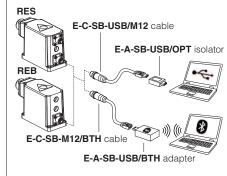
A

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

warning: see ted has been approved

warning: see tech table **GS500** for the list of countries where the Bluetooth adapter

USB or Bluetooth connection



8 SMART TUNING

1 = dvnamic

2 = balanced

3 = smooth

Smart tuning allows to adjust the valve dynamic response in order to match different hydraulic conditions and performance requirements.

The valve is provided with 3 factory settings for the pressure control:

- dynamic fast response time for best dynamic performances. Default factory setting for pressure valves
- balanced average response time suitable for major applications
- **smooth** attenuated response time for slow regulation without overshoots

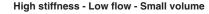
Smart tuning setting can be switched from Dynamic (default) to Balanced or Smooth via software or fieldbus; if requested, performances can be further customized directly tuning each single control parameter. For details consult related manuals E-MAN-RI-* and Quickstart, see section [25].

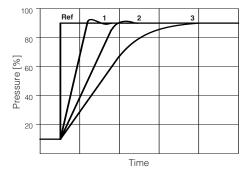
Below indications have to be considered as a general guideline, being affected by hydraulic circuit stiffness, working flow and dead volume.

1 = dvnamic

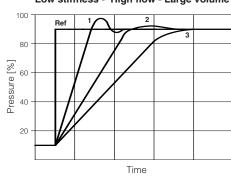
2 = balanced

3 = smooth





Low stiffness - High flow - Large volume



9 FIELDBUS - only for RES, see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These execution allow to operate the valves through fieldbus or analog signals available on the main connector.

10 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index: Ra ≤ 0,8, recommended Ra 0,4 – Flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	75 years, see technical table P007					
Ambient temperature range	R: Standard = -20° C \div +70°C /PE option = -20° C \div +70°C /BT option = -40° C \div +60°C REB, RES: Standard = -20° C \div +60°C /PE option = -20° C \div +60°C /BT option = -40° C \div +60°C					
Storage temperature range	R: Standard = -20°C ÷ +80°C /PE option = -20°C ÷ +80°C /BT option = -40°C ÷ +70°C REB, RES: Standard = -20°C ÷ +70°C /PE option = -20°C ÷ +70°C /BT option = -40°C ÷ +70°C					
Surface protection	Zinc coating with black passivation, galvanic treatment (driver housing for REB and RES)					
Corrosion resistance	Salt spray test (EN ISO 9227) > 200 h					
Compliance	CE according to EMC directive 2014/30/EU (Immunity: EN 61000-6-2; Emission: EN 61000-6-3) RoHS Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

11 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model			LICZO			LIMZO						LIRZO					
valve size		1	2	3	4	5	1	2	3	4	5	6	8	1	2	3	4
Max flow [l/min]			400	750	1000	2000	200	400	750	1000	2000	3000	4500	160	300	550	800
Min regulated pres. at port A [bar]			8,5	8	13	15	7	7	7	7 10,5 12 12 12			12	7			
Min regulated pres. at port A for /350 [bar]			10	10	13	16	10	10	9	12	13	13	16		1	2	
Max regulated pres. at port A	[bar]	100; 210; 315; 350				100; 210; 315; 350						100; 210; 315; 350					
Response time 0-100% step signal (depending on installation) (1) [ms]			80 ÷ 300 80 ÷ 350 80 ÷ 200					200									
Hysteresis [% of the regulated ma	x flow]	≤0,5															
Linearity [% of the regulated max flow]			≤1,0														
Repeatability [% of the regulated max flow]			≤0,2														
Thermal drift		zero point displacement < 1% at ΔT = 40°C															

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 5

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response, see section 9.

12 ELECTRICAL CHARACTERISTICS

Power supplies		: +24 VDC : VRMS = 20 ÷ 32 VMAX	(ripple max 10 % VPP)	
Max power consumption	R = 30 W	REB , RES = 50 W		
Max. solenoid current	2,6 A			
Coil resistance R at 20°C	3 ÷ 3,3 Ω			
Analog input signals	Voltage: range ±10 V Current: range ±20 m	/DC (24 VMAX tollerant) nA	Input impedance Input impedance	
Monitor output	Voltage: maximum rar Current: maximum rar		nax 5 mA nax 500 Ω load resistand	ce
Enable input	Range: 0 ÷ 9 VDC (OFF	state), 15 ÷ 24 VDC (ON :	state), 9 ÷ 15 VDC (not ac	cepted); Input impedance: Ri > 87 k Ω
Fault output		VDC (ON state ≅ VL+ age not allowed (e.g. du		DFF state ≅ 0 V) @ max 50 mA;
Pressure transducer (1)	E-ATR-8/*/I Output	signal: 4 ÷ 20 mA (se	e tech table GS465)	
Alarms			eak with current referendel, pressure transducer	ce signal, over/under temperature, failure
Insulation class			tures of the solenoid coi 982 must be taken into a	
Protection degree to DIN EN60529	R = IP65; REB , RES =	= IP66 / IP67 with mating	connectors	
Duty factor	Continuous rating (ED=	=100%)		
Tropicalization	Tropical coating on ele	ectronics PCB		
Additional characteristics		n of solenoid's current so erse polarity of power so		P.I.D. with rapid solenoid switching;
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT EC 61158
Communication physical layer not insulated USB 2.0 + USB OTG Optical insulated CAN ISO11898 RS485 Fast Ethernet, insulated 100 Base TX			Fast Ethernet, insulated 100 Base TX	
Recommended wiring cable	LiYCY shielded cables	s, see section 21		

- (1) In case of pressure transducer failure, the valve's reaction can be configured through Atos E-SW software to:
 cut off the current to solenoid, therefore the regulated pressure will be reduced to minimum value (default setting)

 - automatically switch the pressure control from closed loop (dynamic, balaced, smooth) to open loop, to let the valve to temporarily operate with reduced regulation accuracy

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

13 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

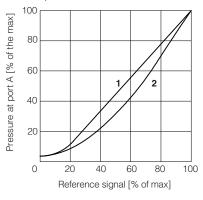
Seals, recommended fluid	d temperature	NBR seals (standard) = $-20^{\circ}\text{C} \div +60^{\circ}\text{C}$ (+80°C for R), with HFC hydraulic fluids = $-20^{\circ}\text{C} \div +50^{\circ}\text{C}$ FKM seals (/PE option) = $-20^{\circ}\text{C} \div +80^{\circ}\text{C}$ NBR low temp. seals (/BT option) = $-40^{\circ}\text{C} \div +60^{\circ}\text{C}$, with HFC hydraulic fluids = $-40^{\circ}\text{C} \div +50^{\circ}\text{C}$			
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at	
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	www.atos.com or KTF catalog	
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, NBR low temp. HL, HLP, HLPD, HVLP, HVLPD		DIN 51524	
Flame resistant without wa	ater	FKM HFDU, HFDR			
Flame resistant with water		NBR, NBR low temp.	HFC	ISO 12922	

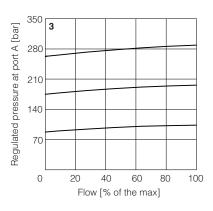


DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

- **Regulation diagrams LIMZO**
- 2 **Regulation diagrams LICZO**

3 Pressure/flow diagrams LICZO, LIMZO





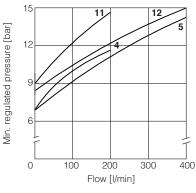
4-14 Min. pressure/flow diagrams

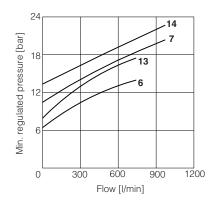
with zero reference signal

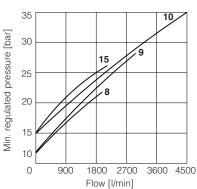
4	= LIMZO-*-1	11 = LICZO-*-1
5	= LIMZO-*-2	12 = LICZO-*-2
6	= LIMZO-*-3	$13 = LICZO^{-*}-3$
7	= LIMZO-*-4	$14 = LICZO^{-*}-4$
Ω	- LIMZO-*-5	15 - LICZO * 5

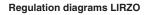
9 = LIMZO-*-6









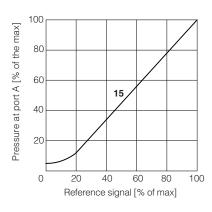


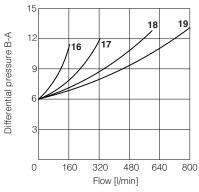
15= LIRZO-A

16-19 Min. pressure/flow diagrams with reference signal "null"

16= LIRZO-*-1 **17**= LIRZO-*-2

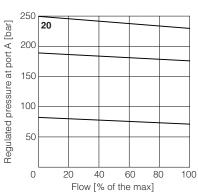
18= LIRZO-*-3 **19**= LIRZO-*-4





Pressure/flow diagrams

20= LIRZO-A



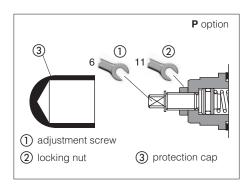
15 HYDRAULIC OPTIONS

P = This option (standard for size 1, 2 and 3) provides a mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded
- turn clockwise the adjustment screw ① until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal
- turn clockwise the adjustment screw (1) of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working



16 ELECTRONIC OPTIONS - only for REB and RES

- = This option provides 4 ÷ 20 mA current reference and monitor signals, instead of the standard 0 ÷ 10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.
- Q = This option permits to inhibit the valve function without removing the power supply to the driver. Upon disable command the current to the solenoid is zeroed and the valve's spool moves to rest position. The option /Q is suggested for all cases where the valve has to be frequently inhibited during the machine cycle - see 19.5 for signal spe-
- Z = This option provides, on the 12 pin main connector, the following additional features:
 Fault output signal see 19.6
 Enable input signal see above option /Q

Power supply for driver's logics and communication - see 19.2

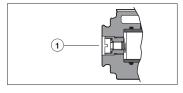
17 POSSIBLE COMBINED OPTIONS

Hydraulic options: all combination possible; Electronics options: /IQ, /IZ

18 AIR BLEEDING

At the first valve commissioning the air eventually trapped inside the solenoid must be bled-off though the screw ① located at the rear side of the solenoid housing.

The presence of air may cause pressure instability and vibrations.



19 POWER SUPPLY AND SIGNALS SPECIFICATIONS - only for REB and RES

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

19.1 Power supply (V+ and V0)

reference)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μF/40 V capacitance to single phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers. In case of separate power supply see 19.2.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

19.2 Power supply for driver's logic and communication (VL+ and VL0) - only for /Z option

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 µF/40 V capacitance to single phase rectifiers or a 4700 µF/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 9 and 10, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

/ A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

19.3 Pressure reference input signal (P_INPUT+)

The driver controls in closed loop the current to the valve pressure proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10 \,\text{VDC}$ for standard and $4 \div 20 \,\text{mA}$ for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of $\pm 10 \,\text{VDC}$ or $\pm 20 \,\text{mA}$. Drivers with fieldbus interface (BC, BP, EH) can be software set to receive reference signal directly by the machine control unit (fieldbus

Analog reference input signal can be used as on-off commands with input range 0 ÷ 24 VDC.

19.4 Pressure monitor output signal (P_MONITOR)

The driver generates an analog output signal proportional to the actual pressure of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, defaults settings are 0 ÷ 10 VDC for standard and 4 ÷ 20 mA for /I option.

Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of 0 ÷ 10 VDC or 0 ÷ 20 mA.

19.5 Enable input signal (ENABLE) - not for standard

To enable the driver, supply a 24 Vpc on pin 3 (pin C): Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

19.6 Fault output signal (FAULT) - only for /Z option

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal broken for 4 ÷ 20 mA input, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal.



20 ELECTRONIC CONNECTIONS

20.1 Main connector signals - 7 pin (A1) Standard and /Q option - for REB and RES

PIN	Standard	/Q	TECHNICAL SPECIFICATIONS	NOTES
Α	A V +		Power supply 24 Vpc	Input - power supply
В	V0		Power supply 0 Vpc	Gnd - power supply
С	AGND		Analog ground	Gnd - analog signal
	ENABLE		Enable (24 Vpc) or disable (0 Vpc) the driver, referred to V0	Input - on/off signal
D	D P_INPUT +		Pressure reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
Е	INPUT-		Negative reference input signal for P_INPUT+	Input - analog signal
F	F P_MONITOR referred to: AGND V0		Pressure monitor output signal: $0 \div 10 \text{ Vpc}$ / $0 \div 20 \text{ mA}$ maximum range Defaults are $0 \div 10 \text{ Vpc}$ for standard and $4 \div 20 \text{ mA}$ for /I option	Output - analog signal Software selectable
G	G EARTH		Internally connected to driver housing	

20.2 Main connector signals - 12 pin (A2) /Z option - for REB and RES

PIN	/Z	TECHNICAL SPECIFICATIONS	NOTES			
1	V+	V+ Power supply 24 Vbc				
2	V0	Gnd - power supply				
3	ENABLE	Input - on/off signal				
4			Input - analog signal Software selectable			
5	INPUT-	Negative reference input signal for INPUT+ Input - analog s				
6	P_MONITOR Pressure monitor output signal: 0 ÷ 10 Vpc / 0 ÷ 20 mA maximum range, referred to VL0 Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option Output - ana Software sei					
7	NC	Do not connect				
8	NC	Do not connect				
9	VL+ Power supply 24 Vpc for driver's logic and communication Input - power s					
10	VLO Power supply 0 Vpc for driver's logic and communication Gnd - power sup					
11	FAULT Fault (0 Vpc) or normal working (24 Vpc), referred to VL0 Output - on/off signal					
PE	EARTH	Internally connected to driver housing				

Note: do not disconnect VL0 before VL+ when the driver is connected to PC USB port

20.3 Communication connectors - for REB (B) and RES (B) - (C)

В	USB con	nector - M12 - 5 pin always present	
PIN	I SIGNAL TECHNICAL SPECIFICATION (1)		
1	+5V_USB	Power supply	
2	ID	Identification	
3	GND_USB	Signal zero data line	
4	D-	Data line -	
5	D+	Data line +	

©2 BP fieldbus execution, connector - M12 - 5 pin (2)				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)		
1	+5V	Termination supply signal		
2	LINE-A	Bus line (high)		
3	DGND	Data line and termination signal zero		
4	LINE-B	Bus line (low)		
5	SHIELD			

(1) Shield connection on connector's housing is recommended

BC fieldbus execution, connector - M12 - 5 pin (2) (C1) PIN SIGNAL **TECHNICAL SPECIFICATION (1)** CAN_SHLD Shield 2 NC do not connect CAN_GND Signal zero data line CAN_H Bus line (high) CAN_L Bus line (low)

©3 (©3 ©4 EH fieldbus execution, connector - M12 - 4 pin (2)				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	TX+	Transmitter			
2	RX+	Receiver			
3	TX-	Transmitter			
4	RX-	Receiver			
Housing	SHIELD				

(2) Only for RES execution

20.4 Solenoid connection - only for R

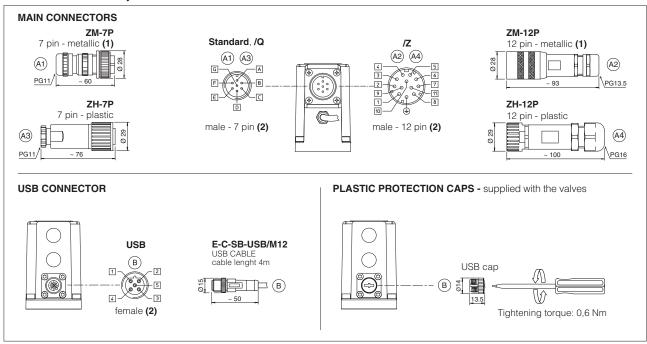
PIN	SIGNAL	TECHNICAL SPECIFICATION	Connector code 666
1	COIL	Power supply	250
2	COIL	Power supply	
3	GND	Ground	

20.5 Pressure transducer connection - only for R

PIN	SIGNAL	TECHNICAL SPECIFICATION	Connector code ZBE-08
1	V+	Power supply	
2	NC	Not connected	2 1
3	TR	Output signal 4 ÷ 20 mA	
4	NC	Not connected	3 4
5	NC	Not connected	5

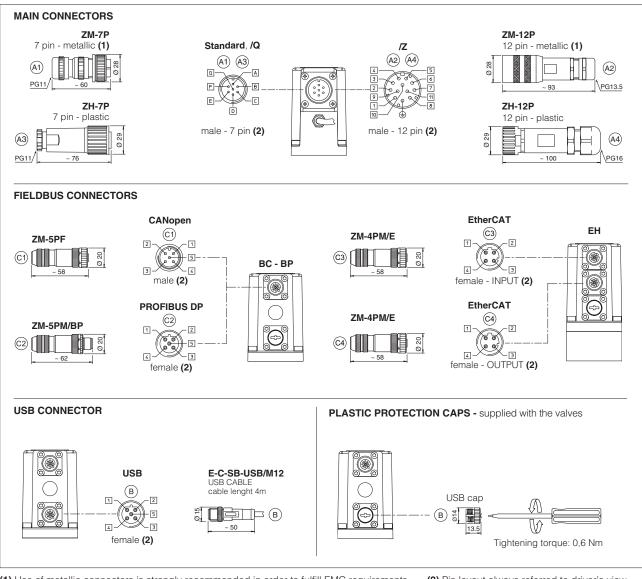


20.6 REB connections layout



(1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements (2) Pin layout always referred to driver's view

20.7 RES connections layout



(1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements (2) Pin lay

(2) Pin layout always referred to driver's view



21 CONNECTORS CHARACTERISTICS - to be ordered separately

21.1 Main connectors - 7 pin - for REB and RES

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY		
CODE	A1 ZM-7P	A3 ZH-7P		
Type 7pin female straight circular		7pin female straight circular		
Standard	According to MIL-C-5015	According to MIL-C-5015		
Material	Metallic	Plastic reinforced with fiber glass		
Cable gland	PG11	PG11		
Recommended cable	LiYCY 7 x 0,75 mm ² max 20 m (logic and power supply) or LiYCY 7 x 1 mm ² max 40 m (logic and power supply)	LiYCY 7 x 0,75 mm² max 20 m (logic and power supply) or LiYCY 7 x 1 mm² max 40 m (logic and power supply)		
Conductor size	up to 1 mm ² - available for 7 wires	up to 1 mm ² - available for 7 wires		
Connection type	to solder	to solder		
Protection (EN 60529)	IP 67	IP 67		

21.2 Main connectors - 12 pin - for REB and RES

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY		
CODE	(A2) ZM-12P	(A4) ZH-12P		
Туре	12pin female straight circular	12pin female straight circular		
Standard	DIN 43651	DIN 43651		
Material	Metallic	Plastic reinforced with fiber glass		
Cable gland	PG13,5	PG16		
Recommended cable	LiYCY 12 x 0,75 mm² max 20 m (logic and power supply)	LiYCY 10 x 0,14mm² max 40 m (logic) LiYY 3 x 1mm² max 40 m (power supply)		
Conductor size	0,5 mm² to 1,5 mm² - available for 12 wires	0,14 mm² to 0,5 mm² - available for 9 wires 0,5 mm² to 1,5 mm² - available for 3 wires		
Connection type	to crimp	to crimp		
Protection (EN 60529)	IP 67	IP 67		

21.3 Fieldbus communication connectors - only for RES

CONNECTOR TYPE	BC CANopen (1)		BP PROFIBUS DP (1)		EH EtherCAT (2)	
CODE	©1 ZM-5PF	©2 ZM-5PM	C1 ZM-5PF/BP	©2 ZM-5PM/BP	C1 C2	ZM-4PM/E
Туре	5 pin female straight circular	5 pin male straight circular	5 pin female straight circular	5 pin male straight circular		4 pin male straight circular
Standard	M12 coding A –	IEC 61076-2-101	M12 coding B – IEC 61076-2-101		M12 co	ding D – IEC 61076-2-101
Material	Metallic		Metallic			Metallic
Cable gland	Pressure nut - cab	Pressure nut - cable diameter 6÷8 mm Pressure nut - cable diameter		le diameter 6÷8 mm	Pressure r	nut - cable diameter 4÷8 mm
Cable	CANbus Standard (DR 303-1) PROFIBL		PROFIBUS	PROFIBUS DP Standard		ernet standard CAT-5
Connection type	Connection type screw terminal		screw terminal			terminal block
Protection (EN 60529)	IF	P67	IP 67			IP 67

⁽¹⁾ E-TRM-** terminators can be ordered separately - see tech table GS500

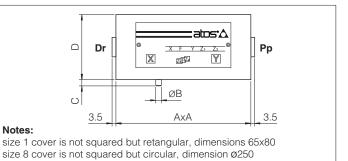
(2) Internally terminated

22 FASTENING BOLTS AND SEALS

Туре	Size	Fastening bolts	Seals
	1 = 16	4 socket head screws M8x45 class 12.9 Tightening torque = 35 Nm	2 OR 108
LIMZO	2 = 25	4 socket head screws M12x45 class 12.9 Tightening torque = 125 Nm	2 OR 108
LIRZO	3 = 32	4 socket head screws M16x55 class 12.9 Tightening torque = 300 Nm	2 OR 2043
	4 = 40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	2 OR 3043
LIMZO LICZO	5 = 50	4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	2 OR 3043
LIMZO	6 = 63	4 socket head screws M30x90 class 12.9 Tightening torque = 2100 Nm	2 OR 3050
	8 = 80	8 socket head screws M24x90 class 12.9 Tightening torque = 1000 Nm	2 OR 4075

23 COVERS DIMENSIONS [mm]

Size	AxA	øВ	С	D	Port Pp - Dr
1 = 16	65x80	3	4	40	-
2 = 25	85x85	5	6	40	-
3 = 32	100×100	5	6	50	-
4 = 40	125x125	5	6	60	G 1/4"
5 = 50	140x140	6	4	70	G 1/4"
6 = 63	180x180	6	4	80	G 3/8"
8 = 80	ø250	8	6	80	G 3/8"

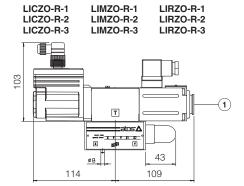




Notes:

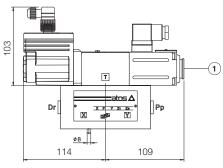


Version ${f R}$ for off-board driver

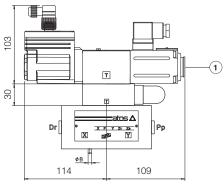


Mass [kg]					
	LICZO, LIMZO,	LIRZO	Cartridge		
Size	Standard	Option /P	SC LI		
1 = 16	3,8	-	0,2		
2 = 25	4,3	-	0,5		
3 = 32	5,6	-	0,9		
4 = 40	11,0	12,0	1,7		
5 = 50	14,5	15,5	2,9		
6 = 63	24,0	25,0	6,7		
8 = 80	32,6	33,6	13,1		

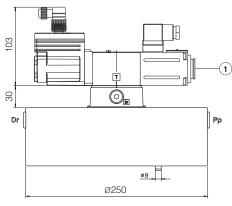
LICZO-R-4 LIMZO-R-4 LIRZO-R-4 LICZO-R-5 LIMZO-R-5 LIMZO-R-6



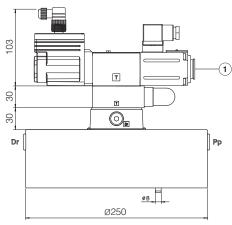




LIMZO-R-8



LIMZO-R-8/P



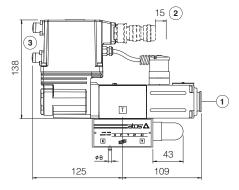
Note: for mounting surface and cavity dimensions, see tech. table P006

1 = Air bleeding, see section 18 •



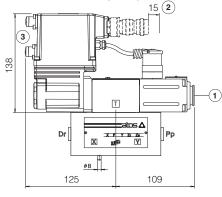
Versions **REB** and **RES** for on-board driver

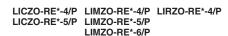
LICZO-RE*-1 LIMZO-RE*-1 LIRZO-RE*-1 LICZO-RE*-2 LIMZO-RE*-2 LIRZO-RE*-2 LICZO-RE*-3 LIMZO-RE*-3 LIRZO-RE*-3

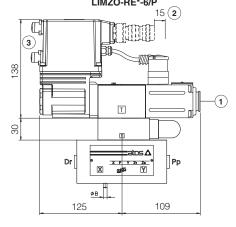


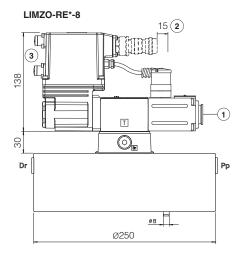
Mass [kg]					
	LICZO, LIMZO, LIRZO				
Size	Standard	Option /P	SC LI		
1 = 16	4,3	-	0,2		
2 = 25	4,8	-	0,5		
3 = 32	6,1	-	0,9		
4 = 40	11,5	12,5	1,7		
5 = 50	15,0	16,0	2,9		
6 = 63	24,5	25,5	6,7		
8 = 80	33,1	34,1	13,1		

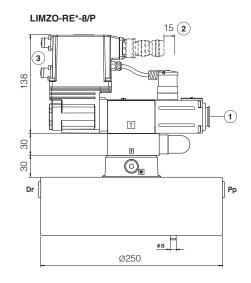
LICZO-RE*-4 LIMZO-RE*-4 LIRZO-RE*-4 LICZO-RE*-5 LIMZO-RE*-5 LIMZO-RE*-6











- 1 = Air bleeding, see section 18
- (2) = Space to remove the connectors
- 3 = The dimensions of all connectors must be considered, see section 20.6 and 20.7

Note: for mounting surface and cavity dimensions, see tech. table P006



Version **RES-EH** for on-board driver Mass [kg] LICZO-RES-EH-1 LIMZO-RES-EH-1 LIRZO-RES-EH-1 LICZO, LIMZO, LIRZO Cartridge LICZO-RES-EH-2 LIMZO-RES-EH-2 LIRZO-RES-EH-2 LICZO-RES-EH-3 LIMZO-RES-EH-3 LIRZO-RES-EH-3 Size Standard Option /P SC LI 15 (2) **1** = 16 4,4 0,2 **2** = 25 4,9 0,5 (3) **3** = 32 6,2 0,9 **4** = 40 11,6 12,6 1,7 63 **5** = 50 15,1 2,9 16,1 **6** = 63 24,6 25,6 6,7 8 = 8033,2 34,2 13,1 Т 43 ØB_ 125 109 LICZO-RES-EH-4/P LIMZO-RES-EH-4/P LIRZO-RES-EH-4/P LIMZO-RES-EH-5/P LIMZO-RE*-6/P LICZO-RES-EH-5/P LIRZO-RES-EH-4 LICZO-RES-EH-4 LIMZO-RES-EH-4 LICZO-RES-EH-5 LIMZO-RES-EH-5 LIMZO-RES-EH-6 15 2 15 (2) 3 (3) 163 63 **(1**) Т 30 Т atos A atos 🛆 X F Y Z1 Z2 øΒ 125 109 125 109 LIMZO-RES-EH-8/P 15 (2) LIMZO-RES-EH-8 15 (2) 3 \mathbb{C} (3) 163 163 **(1**) Т 30 Т 3 30 Dr Dr Pp Pp øв øв Ø250 Ø250 1 = Air bleeding, see section 18 == $(\mathbf{2})$ = Space to remove the connectors

Note: for mounting surface and cavity dimensions, see tech. table P006

(3) = The dimensions of all connectors must be considered, see section 20.6 and 20.7

25 RELATED DOCUMENTATION

FS001	Basics for digital electrohydraulics	P005	Mounting	surfaces for electrohydraulic valves
FS900	Operating and maintenance information for proportional valves	QB400	Quicksta	rt for REB valves commissioning
GS203	E-BM-RES digital driver	QF400	Quicksta	rt for RES valves commissioning
GS500	Programming tools	E-MAN-	BM-RES	RES user manual (off-board)
GS510	Fieldbus	E-MAN-	RI-REB	REB user manual
K800	Electric and electronic connectors	E-MAN-	RI-RES	RES user manual