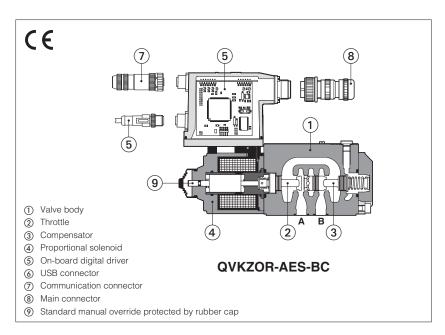


# Digital proportional flow valves

direct, pressure compensated, without transducer



#### QVHZO-A. QVHZO-AEB. QVHZO-AES QVKZOR-A, QVKZOR-AEB, QVKZOR-AES

Proportional flow control valves, direct, pressure compensated without position transducer for open loop flow regulations.

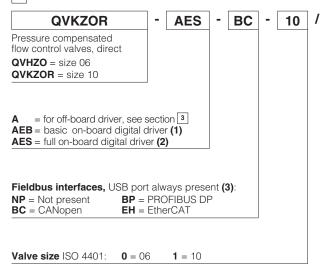
A to be coupled with off-board drivers.

AEB basic execution, with on-board digital driver, analog reference signals and USB port for software functional parameters setting.

AES full execution, with on-board digital driver which includes also fieldbus interface for functional parameters setting, reference signals and real-time diagnostics.

QVHZO: QVKZOR: Size: **06** - ISO 4401 Size: 10 - ISO 4401 Max flow: 90 I/min Max flow: 45 I/min Max pressure: 210 bar Max pressure: 210 bar

#### 1 MODEL CODE



#### Max regulated flow:

QVHZO:		QVKZOR:
3 = 3.5  l/min	<b>36</b> = 35 l/min	<b>65</b> = 65 l/min
<b>12</b> = 12 l/min	<b>45</b> = 45 l/min	<b>90</b> = 90 l/min
<b>18</b> = 18 l/min		

(1) Only for NP

(2) Only for BC, BP, EH

3 way connection

(3) Omit for A execution (4) For possible combined options, see section 15

65

## Seals material, see section 10 = NBR **PE** = FKM Series number BT = HNBR

Coil voltage, only for A - see section 16

= standard coil for 24VDC Atos drivers
 6 = optional coil for 12VDC Atos drivers
 18 = optional coil for low current drivers

#### Hydraulic options (4):

= quick venting of port B

Hand lever options, only for QVHZO-A - see section 13:

MO = horizontal hand lever

MV = vertical hand lever

## Electronics options, only for AEB and AES (4):

- = current feedback for pressure transducer 4÷20 mA
- (omit for std voltage  $0 \div 10$  VDC) only for  $\mathbf{W}$  = current reference input  $4 \div 20$  mA
- (omit for std voltage ±10 VDC)
- = enable signal
- = double power supply, enable, fault and monitor signals -12 pin connector
- = power limitation function 12 pin connector

#### 2 HYDRAULIC SYMBOLS



The valves can be used in 2 or 3 way connection, depending to the application requirements.

In 2 way the P port must not be connected (blocked)

In 3 way the P port has to be connected to tank or to other user lines The port T must be always not connected (blocked)

For application examples of 2 and 3 way connections, see section [12]

Note: hydraulic symbols are rapresented with on-board digital driver



2 way connection

#### 3 OFF-BOARD ELECTRONIC DRIVERS - only for A

Drivers model	E-MI-AC-01F		E-MI-AS-IR		E-BM-AS-PS		E-BM-AES
Туре	Analog			Digital			
Voltage supply (VDC)	12	12 24		24	12	24	24
Valve coil option	/6 std		/6	std	/6	std	std
Format		plug-in to	o solenoid		DIN-rail pa		panel
Tech table	G010		G020		G030		GS050

### 4 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table FS900 and in the user manuals included in the E-SW-\* programming software.

#### 5 VALVE SETTINGS AND PROGRAMMING TOOLS

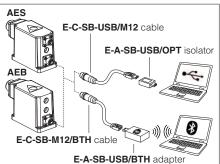
Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table FS900). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

E-SW-BASIC support: NP (USB) PS (Serial) IR (Infrared) **E-SW-FIELDBUS** support: BC (CANopen) BP (PROFIBUS DP) EH (EtherCAT) EW (POWERLINK) EI (EtherNet/IP) **EP (PROFINET)** support: valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ) F-SW-\*/PQ

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection





**USB** or Bluetooth connection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

#### 6 | FIELDBUS - only for AES, see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These execution allow to operate the valves through fieldbus or analog signals available on the main connector.

## 7 GENERAL CHARACTERISTICS

Assembly position	Any position		
Subplate surface finishing to ISO 4401	Acceptable roughness index: Ra ≤ 0,8, recommended Ra 0,4 – Flatness ratio 0,01/100		
MTTFd valves according to EN ISO 13849	150 years, see technical table P007		
Ambient temperature range	A:         Standard = $-20^{\circ}$ C $\div$ +70°C         /PE option = $-20^{\circ}$ C $\div$ +70°C         /BT option = $-40^{\circ}$ C $\div$ +60°C           AEB, AES:         Standard = $-20^{\circ}$ C $\div$ +60°C         /PE option = $-20^{\circ}$ C $\div$ +60°C         /BT option = $-40^{\circ}$ C $\div$ +60°C		
Storage temperature range	A:         Standard = $-20^{\circ}$ C $\div$ +80°C         /PE option = $-20^{\circ}$ C $\div$ +80°C         /BT option = $-40^{\circ}$ C $\div$ +70°C           AEB, AES:         Standard = $-20^{\circ}$ C $\div$ +70°C         /PE option = $-20^{\circ}$ C $\div$ +70°C         /BT option = $-40^{\circ}$ C $\div$ +70°C		
Surface protection	Zinc coating with black passivation, galvanic treatment (driver housing for AEB and AES)		
Corrosion resistance	Salt spray test (EN ISO 9227) > 200 h		
Compliance	CE according to EMC directive 2014/30/EU (Immunity: EN 61000-6-2; Emission: EN 61000-6-3) ROHS Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006		

#### 8 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		QVHZO					QVI	CZOR
Max regulated flow	[l/min]	3,5	12	18	35	45	65	90
Min regulated flow	[cm³/min]	15	20	30	50	60	85	100
Regulating $\Delta p$	[bar]	4	- 6	10	- 12	15	6 - 8	10 - 12
Max flow on port A	[l/min]		40		50	55	70	100
Max pressure	[bar]				210			
Response time 0-100% ste	ep signal [ms]	≤ 30 ≤ 45						
Hysteresis		≤5 [% of the regulated max flow]						
Linearity			≤3 [% of the regulated max flow]					
Repeatability				≤1[% 0	f the regulated	max flow]		

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 3

## 9 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal Rectified and filte	: +24 VDC red : VRMS = 20	÷ 32 VMAX	(ripple	max 10 % VPP)		
May newer consumption		QVHZO				QVKZOR	
Max power consumption	<b>A</b> = 30 W	AEB,	<b>AES</b> = 50 \	٧	<b>A</b> = 35 W		<b>AES</b> = 50 W
Coil voltage code	standard	option /6	option	/18	standard	option /6	option /18
Max. solenoid current	2,2 A	2,75 A	1,2 /	A	2,6 A	3,25 A	1,2 A
Coil resistance R at 20°C	3 ÷ 3,3 Ω	2 ÷ 2,2 Ω	13 ÷ 13	,4 Ω	3,8 ÷ 4,1 Ω	2,2 ÷ 2,4 Ω	12 ÷ 12,5 Ω
Analog input signals	Voltage: range ±		x tollerant)		nput impedance		
Monitor output	Output range:	voltage ±5	VDC @ max	5 mA			
Enable input	Range: 0 ÷ 9 VDC	OFF state), 15 ÷ 2	4 VDC (ON s	state), 9	÷ 15 VDC (not acc	cepted); Input impe	dance: $Ri > 87 \text{ k}\Omega$
Fault output	Output range: 0 external negative	,			11 22 /	FF state ≅ 0 V) @	max 50 mA;
Pressure transducer power supply (only for /W option)	+24VDC @ max 10	00 mA (E-ATR-8 s	ee tech tab	le GS46	55)		
Alarms	Solenoid not conr current control me		,			0 ,	der temperature,
Insulation class	H (180°) Due to the the European star						
Protection degree to DIN EN60529	<b>A</b> = IP65; <b>AEB</b> , <b>A</b>	<b>ES</b> = IP66 / IP67	with mating	conne	ctors		
Duty factor	Continuous rating	(ED=100%)					
Tropicalization	Tropical coating of	on electronics PC	В				
Additional characteristics	Short circuit protection of solenoid's current supply; current control by P.I.D. with rapid solenoid switch protection against reverse polarity of power supply				olenoid switching;		
Communication interface	USB Atos ASCII codine				BUS DP 70-2/IEC61158	EtherCAT EC 61158	
Communication physical layer	not insulated optical insulated optical insulated USB 2.0 + USB OTG CAN ISO11898 RS485 Fast Ethernet, insulated 100 Base TX				ulated		
Recommended wiring cable	LiYCY shielded ca	ables, see section	ղ [19]				

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 Vpc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

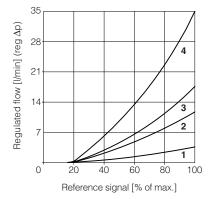
## 10 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

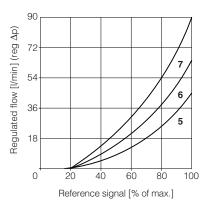
Seals, recommended fluid	I temperature	NBR seals (standard) = $-20^{\circ}\text{C} \div +60^{\circ}\text{C}$ (+80°C for <b>A</b> ), with HFC hydraulic fluids = $-20^{\circ}\text{C} \div +50^{\circ}\text{C}$ FKM seals (/PE option) = $-20^{\circ}\text{C} \div +80^{\circ}\text{C}$ HNBR seals (/BT option) = $-40^{\circ}\text{C} \div +60^{\circ}\text{C}$ , with HFC hydraulic fluids = $-40^{\circ}\text{C} \div +50^{\circ}\text{C}$			
Recommended viscosity		20 ÷ 100 mm²/s - max allowed r	ange 15 ÷ 380 mm²/s		
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at		
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	www.atos.com or KTF catalog	
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM HFDU, HFDR		ISO 12922	
Flame resistant with water		NBR, HNBR	HFC	130 12922	



#### 11.1 Regulation diagrams

- 1 = QVHZO-\*-06/3
- 2 = QVHZO-\*-06/12
- 3 = QVHZO-\*-06/18
- 4 = QVHZO-\*-06/36
- 5 = QVHZO-\*-06/45
- 6 = QVKZOR-\*-10/65 7 = QVKZOR-\*-10/90



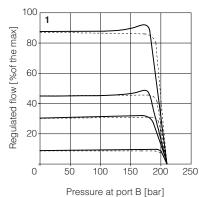


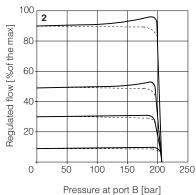
#### 11.2 Regulated flow/outlet pressure diagrams

with inlet pressure = 210 bar

- 1 = QVHZO
- $\mathbf{2} = \mathsf{QVKZOR}$

Dotted line for 3-way versions

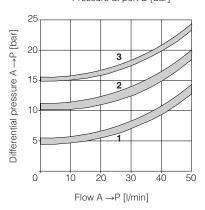


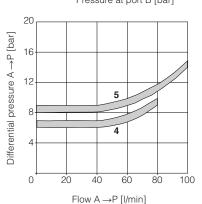


### 11.3 Flow A →P/∆p diagrams

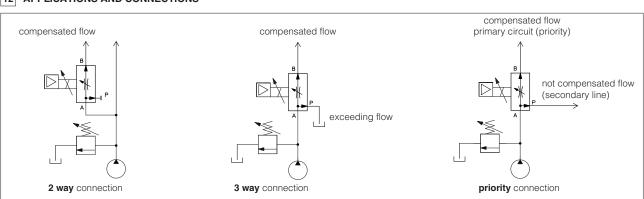
3-way configuration

- 1 = QVHZO-\*-06/3
- QVHZO-\*-06/12 2 = QVHZO-\*-06/18
- QVHZO-\*-06/36
- 3 = QVHZO-\*-06/45
- 4 = QVKZOR-\*-10/65
- 5 = QVKZOR-\*-10/90





## 12 APPLICATIONS AND CONNECTIONS



## 2 way connection

The 2 way connection is normally used to control the flow in one part of the hydraulic circuit or to regulate the speed of a specific actuator. The metered flow in the controlled line is kept constant, independently to the load variations

If the valve is directly installed on the pump main line, the exceeding flow is returned to tank though the pressure relief valve.

## 3 way connection

The 3 way connection is normally used when the valve directly controls the pump flow (main line).

The metered flow in the controlled line is kept constant, independently to the load variations.

The exceeding flow (not metered by the valve) it is returned to tank trough the valve P port = T line (3rd way).

## **Priority connection**

The priority connection guarantees the pressure compensated flow supply to the primary circuit.

The exceeding flow (not required by the primary circuit) is bypassed through the valve P port, to secondary circuit operating at lower pressure and not requiring compensated flow regulations.



#### 13 HYDRAULIC OPTIONS

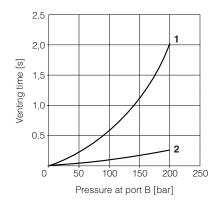
D = This option provides a quick venting of the use port B when the valve is closed or de-energized.

The valve must be connected in 3 way, with P port connected to tank. When the proportional throttle is fully closed, the valve's port B is internally connected to port P (tank), permitting a quickly decompression of the pressure in the use line.

In the diagram aside are represented the venting times of **QVHZO** and **QVKZOR** with option /D respect to standard versions:

1 = standard version

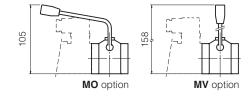
2 = option /Q



#### Hand lever option - only for QVHZO-A

It allows to operate the valve in absence of electrical power supply. For detailed description of QVHZO-A with hand lever option see tech. table **E138**.

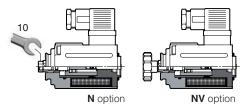
**MO** = Horizontal hand lever **MV** = Vertical hand lever



The following supplementary options allow to operate **QVHZO-A** and **QVKZOR-A** in absence of electrical power supply by means of a micrometric screw replacing the standard solenoid manual override, see tech. table **TK150** 

**N** = Manual micrometric adjustment

NV = As option /N plus handwheel and graduated scale



## 14 ELECTRONICS OPTIONS - only for AEB and AES

- I = This option provides 4 ÷ 20 mA current reference and monitor signals, instead of the standard ±10 VDC.
  Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.
  It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.
- Q = This option permits to inhibit the valve function without removing the power supply to the driver. Upon disable command the current to the solenoid is zeroed and the valve's spool moves to rest position.
  The option /Q is suggested for all cases where the valve has to be frequently inhibited during the machine cycle see 17.5 for signal specifications.
- **Z** = This option provides, on the 12 pin main connector, the following additional features:

Fault output signal - see 17.6

Enable input signal - see above option /Q

Power supply for driver's logics and communication - see 17.2

**C** = Only in combination with option /W

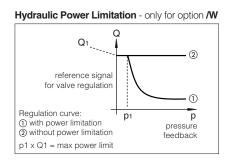
This option is available to connect pressure transducers with  $4 \div 20$  mA current output signal, instead of the standard  $\pm 10$  VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDC or  $\pm 20$  mA.

**W** = Only for valves coupled with pressure compensator, see tech table **D150**.

It provides the hydraulic power limitation function. The driver receives the flow reference signal by the analog input INPUT+ and a pressure transducer, installed in the hydraulic system, has to be connected to the driver's analog input TR. When the actual requested hydraulic power  $\mathbf{p} \mathbf{x} \mathbf{Q}$  (TR x INPUT+) reaches the max power limit (p1xQ1), internally set by software, the driver automatically reduces the flow regulation of the valve.

The higher is the pressure feedback the lower is the valve's regulated flow:

Flow regulation = Min (  $\frac{\text{PowerLimit [sw setting]}}{\text{Transducer Pressure [TR]}}$ ; Flow Reference [INPUT+])



#### 15 POSSIBLE COMBINED OPTIONS

**Hydraulic options**: all combination possible **Electronics options**: /IQ, /IZ, /IW, /CW, /CWI



#### 16 COIL VOLTAGE OPTIONS - only for A

6 = Optional coil to be used with Atos drivers with power supply 12 VDC.

18 = Optional coil to be used with electronic drivers not supplied by Atos.

#### 17 POWER SUPPLY AND SIGNALS SPECIFICATIONS - only for AEB and AES

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

#### 17.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers. In case of separate power supply see 17.2.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

#### 17.2 Power supply for driver's logic and communication (VL+ and VL0) - only for /Z and /W options

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 9 and 10, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

### 17.3 Reference input signal (INPUT+)

The driver controls in closed loop the current to the valve proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are  $0 \div 10 \text{ Vpc}$  for standard and  $4 \div 20 \text{ mA}$  for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10 \text{ Vpc}$  or  $\pm 20 \text{ mA}$ . Drivers with fieldbus interface (BC, BP, EH) can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range  $0 \div 24 \text{Vpc}$ .

#### 17.4 Monitor output signals (MONITOR and MONITOR2)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, default settings is 0 ÷ 5 Vpc (1V = 1A).

Output signal can be reconfigured via software, within a maximum range of  $\pm 5~\text{Vpc}$ .

#### Option /W

The driver generates a second analog output signal (MONITOR2) proportional to the actual system pressure.

The output maximum range is ±5 Vpc; default setting is 0 ÷ 5 Vpc.

#### 17.5 Enable input signal (ENABLE) - not for standard

To enable the driver, supply a 24 Vpc on pin 3 (pin C): Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849.

Enable input signal can be used as generic digital input by software selection.

## 17.6 Fault output signal (FAULT) - only for $\mbox{/Z}$ and $\mbox{/W}$ options

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal broken for 4 ÷ 20 mA input, etc.). Fault presence corresponds to 0 Vpc, normal working corresponds to 24 Vpc.

Fault status is not affected by the Enable input signal.

#### 17.7 Remote pressure transducer input signal (TR+) - only for /W option

Analog pressure transducers can be directly connected to the driver (see 18.4).

Analog input signal is factory preset according to selected driver code, defaults are  $0 \div 10 \text{ Vpc}$  for standard and  $4 \div 20 \text{ mA}$  for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10 \text{ Vpc}$  or  $\pm 20 \text{ mA}$ . Note: transducer feedback can be read as a digital information through fieldbus communication - software selectable.



## 18 ELECTRONIC CONNECTIONS

## 18.1 Main connector signals - 7 pin $\stackrel{\hbox{\scriptsize (A)}}{}$ Standard and $^{\prime}$ Q option - for AEB and AES

PIN	Standard	tandard /Q TECHNICAL SPECIFICATIONS		NOTES
Α	A <b>V</b> +		Power supply 24 Vpc	Input - power supply
В	V0		Power supply 0 Vpc	Gnd - power supply
С	AGND		Analog ground	Gnd - analog signal
	ENABLE		Enable (24 VDC) or disable (0 VDC) the driver, referred to V0	Input - on/off signal
D	D INPUT+		Reference input signal: $\pm 10$ Vpc / $\pm 20$ mA maximum range Defaults are $0 \div 10$ Vpc for standard and $4 \div 20$ mA for /I option	Input - analog signal Software selectable
Е	E INPUT-		Negative reference input signal for INPUT+	Input - analog signal
F	F MONITOR referred to: AGND   V0		Monitor output signal: ±5 Vpc maximum range Default is 0 ÷ 5 Vpc (1V = 1A)	Output - analog signal <b>Software selectable</b>
G	G <b>EARTH</b>		Internally connected to driver housing	

## 18.2 Main connector signals - 12 pin $\stackrel{\hbox{\scriptsize (A)}}{}$ /Z and /W options - for AEB and AES

PIN	/Z	/W	TECHNICAL SPECIFICATIONS	NOTES
1	V+		Power supply 24 Vpc	Input - power supply
2	V0		Power supply 0 Vpc	Gnd - power supply
3	ENABLE		Enable (24 VDC) or disable (0 VDC) the driver, referred to VL0	Input - on/off signal
4	INPUT+		Reference input signal: $\pm 10$ Vpc / $\pm 20$ mA maximum range Defaults are $0 \div 10$ Vpc for standard and $4 \div 20$ mA for /I option	Input - analog signal Software selectable
5	INPUT-		Negative reference input signal for INPUT+	Input - analog signal
6	6 MONITOR		Monitor output signal: $\pm 5$ Vpc maximum range, referred to VL0 Default is $0 \div 5$ Vpc (1V = 1A)	Output - analog signal <b>Software selectable</b>
7	NC		Do not connect	
8	NC		Do not connect	
0		MONITOR2	2nd monitor output signal: ±5 Vpc maximum range, referred to VLO. Default is 0 ÷ 5 Vpc	Output - analog signal
9	VL+		Power supply 24 Vpc for driver's logic and communication	Input - power supply
10	0 <b>VL0</b>		Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
11	1 FAULT		Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
PE	EARTH		Internally connected to driver housing	

Note: do not disconnect VL0 before VL+ when the driver is connected to PC USB port

## **18.3 Communication connectors** - for **AEB** (B) and **AES** (B) - (C)

В	B USB connector - M12 - 5 pin always present				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	+5V_USB	Power supply			
2	ID	Identification			
3	GND_USB	Signal zero data line			
4	D-	Data line -			
5	D+	Data line +			

©2)	©2 BP fieldbus execution, connector - M12 - 5 pin (2)			
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)		
1	+5V	Termination supply signal		
2	LINE-A	Bus line (high)		
3	DGND	Data line and termination signal zero		
4	LINE-B	Bus line (low)		
5	SHIELD			

(1) Shield connection on connector's housing is recommended

(C1)	BC fieldbus execution, connector - M12 - 5 pin (2)			
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)		
1	CAN_SHLD	Shield		
2	NC	do not connect		
3	CAN_GND	Signal zero data line		
4	CAN_H	Bus line (high)		
5	CAN_L	Bus line (low)		

©3 (	©3 ©4 EH fieldbus execution, connector - M12 - 4 pin (2)				
PIN SIGNAL TECHNICAL SPECIFICATION (1)					
1	TX+	Transmitter			
2	RX+	Receiver			
3	TX-	Transmitter			
4	RX-	Receiver			
Housing	SHIELD				

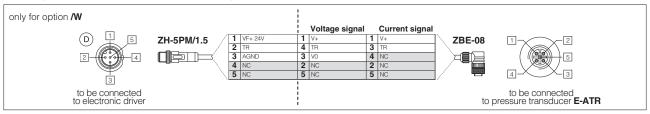
(2) Only for AES execution



#### 18.4 Remote pressure transducer connector - M12 - 5 pin - only for /W option - for AEB and AES (D)

PIN	SIGNAL	TECHNICAL SPECIFICATION	Voltage	Current
1	VF +24V	Power supply +24Vpc	Connect	Connect
2	TR	Signal transducer maximum range $\pm 10$ Vpc / $\pm 20$ mA, software selectable Defaults are 0 $\div$ 10 Vpc for standard and 4 $\div$ 20 mA for /C option	Connect	Connect
3	AGND	Common GND for transducer power and signals	Connect	/
4	NC	Not Connect	/	/
5	NC	Not Connect	/	/

#### Remote pressure transducer connection - example

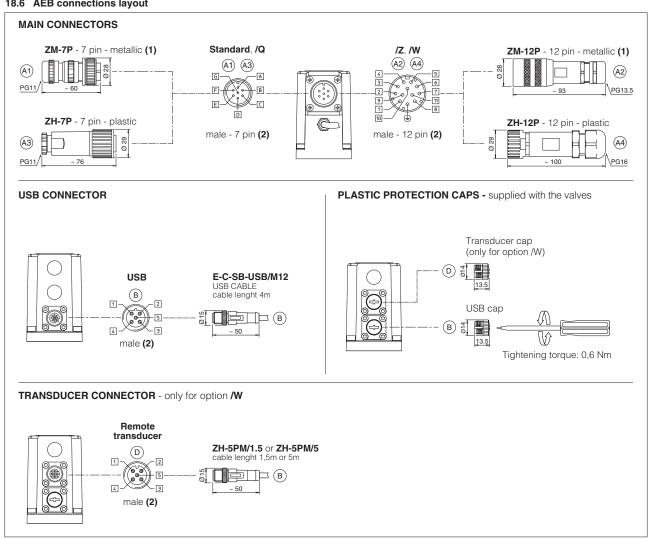


Note: connectors front view

#### 18.5 Solenoid connection - only for A

PIN	SIGNAL	TECHNICAL SPECIFICATION	Connector code 666		
1	COIL	Power supply	250		
2	COIL	Power supply			
3	GND	Ground			

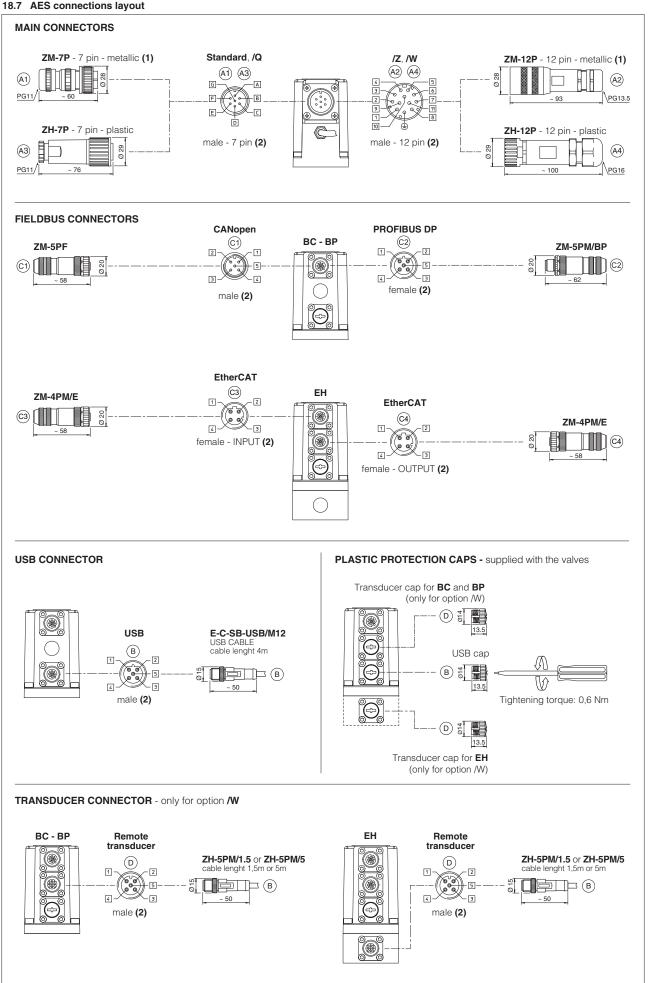
### 18.6 AEB connections layout



(1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements

(2) Pin layout always referred to driver's view





(1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements

(2) Pin layout always referred to driver's view



## 19 CONNECTORS CHARACTERISTICS - to be ordered separately

### 19.1 Main connectors - 7 pin - for AEB and AES

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY	
CODE	A1) ZM-7P	A3 ZH-7P	
Type 7pin female straight circular		7pin female straight circular	
Standard	According to MIL-C-5015	According to MIL-C-5015	
Material	Metallic	Plastic reinforced with fiber glass	
Cable gland	PG11	PG11	
Recommended cable	LiYCY 7 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply) or LiYCY 7 x 1 mm <sup>2</sup> max 40 m (logic and power supply)	LiYCY 7 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply) or LiYCY 7 x 1 mm <sup>2</sup> max 40 m (logic and power supply)	
Conductor size	up to 1 mm <sup>2</sup> - available for 7 wires	up to 1 mm <sup>2</sup> - available for 7 wires	
Connection type	to solder	to solder	
Protection (EN 60529)	IP 67	IP 67	

## 19.2 Main connectors - 12 pin - for AEB and AES

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY
CODE	A2 ZM-12P	(A4) ZH-12P
Туре	12pin female straight circular	12pin female straight circular
Standard	DIN 43651	DIN 43651
Material	Metallic	Plastic reinforced with fiber glass
Cable gland	PG13,5	PG16
Recommended cable	LiYCY 12 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply)	LiYCY 10 x 0,14mm² max 40 m (logic) LiYY 3 x 1mm² max 40 m (power supply)
Conductor size	0,5 mm² to 1,5 mm² - available for 12 wires	0,14 mm² to 0,5 mm² - available for 9 wires 0,5 mm² to 1,5 mm² - available for 3 wires
Connection type	to crimp	to crimp
Protection (EN 60529)	IP 67	IP 67

## 19.3 Fieldbus communication connectors - only for AES

CONNECTOR TYPE BC CANopen (1)		BP PROFIBUS DP (1)		EH EtherCAT (2)		
CODE	C1 ZM-5PF	©2 <b>ZM-5PM</b>	C1 ZM-5PF/BP	©2 ZM-5PM/BP	C1 C2	ZM-4PM/E
Туре	5 pin female straight circular	5 pin male straight circular	5 pin female straight circular	5 pin male straight circular		4 pin male straight circular
Standard M12 coding A – IEC 61076-2-101		M12 coding B – IEC 61076-2-101		M12 co	ding D – IEC 61076-2-101	
Material Metallic		Metallic			Metallic	
Cable gland Pressure nut - cable diameter 6÷8 mm		Pressure nut - cable diameter 6÷8 mm		Pressure r	nut - cable diameter 4÷8 mm	
Cable	CANbus Stand	dard (DR 303-1)	PROFIBUS DP Standard		Ethe	ernet standard CAT-5
Connection type	screw	terminal	screw terminal			terminal block
Protection (EN 60529) IP67		IP 67		IP 67		

<sup>(1)</sup> E-TRM-\*\* terminators can be ordered separately - see tech table  ${\bf GS500}$ 

(2) Internally terminated

#### 19.4 Pressure transducer connectors - only for /W option

CONNECTOR TYPE	TRANSDUCER			
CODE	D1 ZH-5PM/1.5	D1 ZH-5PM/5		
Туре	5 pin male straight circular			
Standard	M12 coding A – IEC 61076-2-101			
Material	Plastic			
Cable gland	Connector moulded on cables			
Cable glariu	1,5 m lenght	5 m lenght		
Cable	5 x 0,25 mm <sup>2</sup>			
Connection type	molded cable			
Protection (EN 60529)	IP 67			

## 20 FASTENING BOLTS AND SEALS

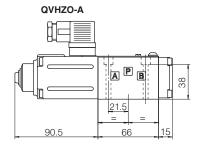
	QVHZO	QVKZOR
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108 Diameter of ports A, B, P, T: Ø 7,5 mm	Seals: 5 OR 2050 Diameter of ports A, B, P, T: Ø 11,2 mm

## 21 INSTALLATION DIMENSIONS FOR QVHZO [mm]

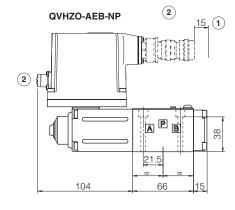
ISO 4401: 2005

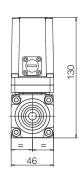
Mounting surface: 4401-03-02-0-05 (see tab. P005)

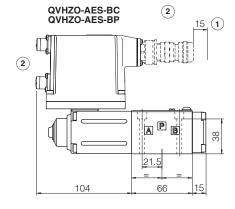
Mass [kg]			
Α	AEB, AES	AES-EH	
2,3	2,8	2,9	

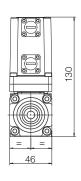


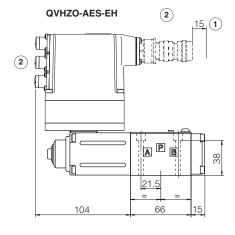


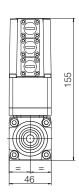












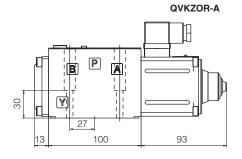
- 1 = Space to remove the connectors
- (2) = The dimensions of all connectors must be considered, see section 18.6 and 18.7

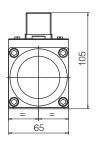
## 22 INSTALLATION DIMENSIONS FOR QVHZOR [mm]

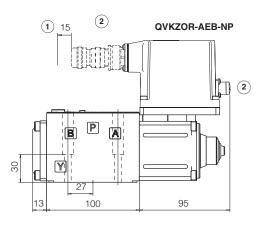
ISO 4401: 2005

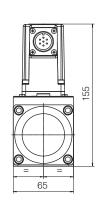
Mounting surface: 4401-05-04-0-05 (see tab. P005)

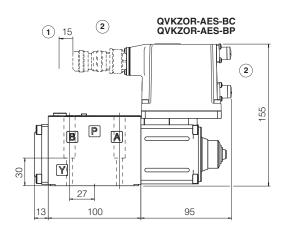
Mass [kg]				
Α	AEB, AES	AES-EH		
3,8	4,3	4,4		

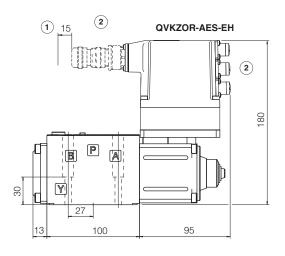












- 1 = Space to remove the connectors
- (2) = The dimensions of all connectors must be considered, see section 18.6 and 18.7

## 23 RELATED DOCUMENTATION

FS001	Basics for digital electrohydraulics	GS510	Fieldbus
FS900	Operating and maintenance information for proportional valves	K800	Electric and electronic connectors
G010	E-MI-AC analog driver	P005	Mounting surfaces for electrohydraulic valves
G020	E-MI-AS-IR digital driver	QB200	Quickstart for AEB valves commissioning
G030	E-BM-AS digital driver	QF200	Quickstart for AES valves commissioning
GS050	E-BM-AES digital driver		



**GS500** Programming tools